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Filling Temporal Gaps within and between GRACE and GRACE-FO Terrestrial Water Storage Records: An Innovative Approach

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Abstract: Temporal gaps within the Gravity Recovery and Climate Experiment (GRACE) (gap: 20 months), between GRACE and GRACE Follow-On (GRACE-FO) missions (gap: 11 months), and within GRACE-FO record (gap: 2 months) make it difficult to analyze and interpret spatiotemporal variability in GRACE- and GRACE-FO-derived terrestrial water storage (TWS_{GRACE}) time series. In this study, an overview of data and approaches used to fill these gaps and reconstruct the TWS_{GRACE} record at the global scale is provided. In addition, the study provides an innovative approach that integrates three machine learning techniques (deep-learning neural networks [DNN], generalized linear model [GLM], and gradient boosting machine [GBM]) and eight climatic and hydrological input variables to fill these gaps and reconstruct the TWS_{GRACE} data record at both global grid and basin scales. For each basin and grid cell, the model performance was assessed using Nash–Sutcliffe efficiency coefficient (NSE), correlation coefficient (CC), and normalized root-mean-square error (NRMSE), a leader model was selected based on the model performance, and variables that significantly control leader model outputs were defined. Results indicate that (1) the leader model reconstructed the TWS_{GRACE} with high accuracy over both grid and local scales, particularly in wet and low anthropogenically active regions (grid scale: $NSE = 0.65 \pm 0.20$, $CC = 0.81 \pm 0.13$, and $NSE = 0.56 \pm 0.16$; basin scale: $NSE = 0.78 \pm 0.14$, $CC = 0.89 \pm 0.07$, and $NRMSE = 0.43 \pm 0.14$); (2) no single model was flawless in reconstructing the TWS_{GRACE} over all grids or basins, so a combination of models is necessary; (3) basin-scale models outperform grid-scale models; (4) the DNN model outperforms both GLM and GBM at the basin scale, whereas the GBM outperforms at the grid scale; (5) among other inputs, the Global Land Data Assimilation System (GLDAS)-derived TWS controls the model performance on both basin and grid scales; and (6) the reconstructed TWS_{GRACE} data captured extreme climatic events over the investigated basins and grid cells. The developed approach is robust, effective, and could be used to accurately reconstruct TWS_{GRACE} for any hydrologic system across the globe.

Keywords: GRACE; GRACE-FO; gap filling; grid scale; basin scale; machine learning



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1. Introduction

The Gravity Recovery and Climate Experiment (GRACE) mission launched jointly by the U.S. National Aeronautics and Space Administration and the German Aerospace Center on 17 March 2002 was designed to map both spatial variability in the Earth's static gravity field and the spatiotemporal variations in Earth's gravity field with unprecedented accuracy [1]. The spatiotemporal variability in gravity field solutions delivered by the GRACE mission is directly related to the natural and anthropogenic variations in terrestrial water storage (TWS) components such as surface water, groundwater, soil moisture,

permafrost, snow, ice, and wet biomass [2]. The GRACE-derived TWS (TWS_{GRACE}) empowers the scientific community to address previously unresolvable questions in hydrology, oceanology, cryosphere, and solid Earth fields at both regional and global scales [3–21]. However, the global monthly TWS_{GRACE} record (April 2002–June 2017) suffers from temporal gaps (20 months) caused by battery performance issues with approximately 10% of the TWS_{GRACE} record missing.

Because of the impressive success of the GRACE mission, the GRACE Follow-On (GRACE-FO) mission launched in May 2018 and is continuing the extremely successful work of its predecessor [22]. However, there is an 11-month gap in TWS data (July 2017–May 2018) between the two missions. Two additional months are missing from the current GRACE-FO record (August 2018–September 2018). Currently, an estimated 15% of the available TWS_{GRACE} data record is missing from the combined GRACE and GRACE-FO missions (April 2002–April 2021). In this study, the term TWS_{GRACE} refers to both the GRACE- and GRACE-FO-derived TWS records (i.e., the combined data record).

Similar to any other temporal dataset, temporal gaps in TWS_{GRACE} hinder their analysis and interpretation [23–25]. Gaps in TWS_{GRACE} introduce errors in amplitude and phase of the annual cycle, residual variabilities, and secular trends, and increase the level of uncertainty in their spectral modeling [26]. Long gaps could also obscure the temporal patterns of TWS data and consequently distort the results of any statistical analysis [27].

In this article, we provide an overview of previous approaches that have been used to reconstruct, and/or fill gaps in the TWS_{GRACE} record and discuss the advantages and limitations of each approach. In addition, we provide an innovative approach to fill current gaps in the TWS_{GRACE} record, between GRACE and GRACE-FO missions, and within the GRACE-FO record. Specifically, three machine learning techniques (generalized linear model [GLM], gradient boosting machine [GBM], and deep-learning neural networks [DNN]) and eight climatic and hydrological input variables were integrated and used to reconstruct TWS_{GRACE} data at both the grid ($1^\circ \times 1^\circ$; total grid points: 14,310) and basin (62 global watersheds; Figure 1) scales. For each basin and grid cell, the model performance was assessed for GLM, GBM, and DNN models, and a “leader model” was selected. In this article, the leader model is defined as the model that combines the best (highest statistical performance during the testing phase) of the three models. Model inputs that significantly control TWS_{GRACE} variability in each basin and grid were also identified.

2. Filling Temporal Gaps in TWS_{GRACE} Record: An Overview

Several studies have been conducted to reconstruct the TWS_{GRACE} using different datasets and approaches at both grid and basin scales (Table 1). Datasets that have been used to reconstruct the TWS_{GRACE} include measured and modeled hydroclimatic and/or gravimetric datasets. The hydroclimate variables were used to reconstruct TWS_{GRACE} by correlating the spatiotemporal variability in these variables with the spatiotemporal variability in TWS_{GRACE} . Examples of the climatic variables include, but are not limited to, temperature, rainfall, sea surface temperature, and climate indices [25,28–37]. Hydrological variables include soil moisture, runoff, water level, and evapotranspiration [25,33,34,36,38–42].

Gravimetric datasets from various low Earth orbiting (LEO) satellite missions were used to reconstruct, and fill gaps within, the TWS_{GRACE} . For instance, the Geodetic satellite laser ranging (SLR) data that provide temporal variations of the Earth’s gravity field at the lowest degrees of the spherical harmonic spectrum were used to fill the gap in TWS_{GRACE} [37,43–46]. Low-resolution gravity models derived from the European Space Agency (ESA)’s Swarm satellite were used to recover the temporal variations in Earth’s gravity field [47] and reconstruct the TWS_{GRACE} [48–50]. These products, however, have very coarse resolution (~ 1500 km) compared to TWS_{GRACE} data [42], which limits their application in reconstruction TWS_{GRACE} data.

Several techniques used TWS_{GRACE} data along with different hydroclimatic and hydrologic variables to fill TWS_{GRACE} data gaps. These include interpolation, signal decom-

position, use of land surface models (LSMs) outputs, water balance, data assimilation, and statistical and data mining techniques (Table 1).

Interpolation of the neighboring months has been widely used to fill TWS_{GRACE} data gaps [7,8,27]. Linear interpolation techniques, however, are less accurate in mapping non-linear systems such as TWS_{GRACE} [51], especially where two or more successive monthly values are missing (e.g., 11-month gap between the GRACE and GRACE-FO missions). In addition, other interpolation techniques (e.g., spline) are less accurate at mapping extreme values such as those associated with droughts and floods, and they usually suffer from smoothing effects [52].

The Singular Spectrum Analysis (SSA) techniques have been used to fill the missing TWS_{GRACE} data [50,53–55] given that SSA is able to extract significant information from short and noisy time series by decomposing it into a trend, annual/seasonal signal, and noise without any prior physical and dynamical knowledge that affects time series [56]. However, SSA is reported to have distorted reconstruction results [50].

LSM-derived TWS outputs have also been used as proxies for TWS_{GRACE} data. This approach, however, depends on the degree to which these models can simulate natural episodic events (e.g., droughts or floods), which in turn are dependent on the physics and structure of these LSMs, and on the resolution, coverage, and accuracy of the meteorological forcing datasets [57]. A recent study over Africa [3] indicated that some of the LSMs result in overestimation of winter TWS values and underestimates of summer values when compared to TWS_{GRACE} . Globally, LSMs underestimate TWS_{GRACE} trends [58] and are unable to capture seasonal TWS_{GRACE} amplitudes [59]. Although such models can potentially simulate TWS_{GRACE} variabilities caused by natural phenomena, they are also less successful at simulating variabilities caused by anthropogenic influences because these forcings are typically not captured in the LSMs inputs [60–63].

Table 1. Review of previous TWS_{GRACE} reconstruction data and techniques.

Reference	Scale/Region	Approach †	Inputs *
Becker et al. [38]	Grid (Amazon)	Correlation	GRACE, Water level
Pan et al. [36]	Basin (global)	Data assimilation	GRACE, LSM, P, ET
De Linage et al. [35]	Basin (Amazon)	MLR	Pacific and Atlantic SST
Long et al. [33]	Basin (Southwest China)	ANN	SMS, P, T
Forootan et al. [29]	Basin/Grid (West Africa)	ICA, ARX	SST, P
Sośnica et al. [46]	Grid (global)	LR	SLR, GRACE
Zhang et al. [64]	Basin (Yangtze)	ANN	SMS
Nie et al. [65]	Basin (Amazon)	LR	GRACE, GLDAS
Talpe et al. [43]	Grid (Greenland and Antarctica)	PCA	SLR, GRACE
Humphrey et al. [30]	Grid (global)	MLR	P, T
Yang et al. [41]	Basin (NW China)	ANN, GLM, RF, SVM	GRACE, GLDAS
Chen et al. [28]	Basin (Northeast China)	GRNN	P, T
Ahmed et al. [25]	Basin (Africa)	NARX	P, ET, NDVI, T
Hasan et al. [39]	Basin (Africa)	ARX	GLDAS, ENSO
Yin et al. [34]	Basin (China)	MLR	P, ET, runoff
Meyer et al. [49]	Grid (Arctic and Antarctic)	LR	SLR, Swarm, GRACE
Humphrey and Gudmundsson [66]	Grid (global)	MLR	GRACE, P
Ferreira et al. [67]	Grid (West Africa)	NARX	P, ET, T, SMS, climate indices
Sun et al. [68]	Grid (India)	CNN	GRACE, GLDAS

Table 1. Cont.

Reference	Scale/Region	Approach †	Inputs *
Li et al. [53]	Basin (China)	SSA, ARIMA	GRACE, GLDAS
Jing et al. [69]	Basin (Nile)	RF, XGB	GRACE, GLDAS
Kenea et al. [31]	Basin (Ethiopia)	ESM	SST, P
Jing et al. [40]	Basin (China)	RF, LR	GRACE, GLDAS
Zhu et al. [70]	Grid (global)	SSA	GRACE
Li et al. [32]	Grid/Basin (global)	MLR, ANN, ARX	P, T, SST, climate indices
Forootan et al. [48]	Grid/Basin (global)	ICA	GRACE, Swarm
Sun et al. [71]	Grid/Basin (global)	DNN, MLR, SARIMAX	GRACE, GLDAS, P, T
Sohoulande et al. [72]	Grid (United States)	MVS	P, T, potential ET
Jing et al. [73]	Basin (regional)	RF, XGB	CRU, GLDAS
Sun et al. [42]	Grid/Basin (United States)	AutoML	GLDAS, climate indices, P, T
Li et al. [37]	Grid (global)	ANN, ARX, MLR	P, SST, T, climate indices
Jeon et al. [74]	Grid/Basin (global)	CNN	T, ET, P
Yu et al. [75]	Grid (Canada)	CNN	GRACE, EALCO-TWS
Tang et al. [76]	Basin (Lancang-Mekong)	RF	GLDAS, CRU
Yang et al. [77]	Grid (Australia)	LSR	GRACE, modeled TWS
Wang et al. [55]	Basin (Global)	SSA	GRACE, Swarm
Löcher and Kusche [45]	Grid (global)	EOF	SLR
Yi and Sneeuw [52]	Grid/Basin (global)	SSA	Swarm, GRACE
Gyawali et al. [20]	Basin (Texas coast)	ANN, MLR	P, T, NLDAS-TWS
Mo et al. [78]	Grid/Basin (Global)	BCNN	P, T, ERA5L-TWSA, CWSC

† ANN: artificial neural network; DNN: deep neural network; CNN: convolutional neural network; BCNN: Bayesian convolutional neural networks; GLM: generalized linear model; SVM: support vector machines; RF: random forest; MLR: multilinear regression; XGB: extreme gradient boosting; AutoML: automated machine learning; ARX: autoregressive exogenous; NARX: nonlinear autoregressive with exogenous; SARIMA: seasonal auto-regressive integrated moving average with exogenous variables; GRNN: general regression neural network; SSA: singular spectrum analysis; ICA: Independent component analysis; ESM: empirical statistical model; LR: linear regression; MVS: multivariate statistics; LSR: least square regression; EOF: empirical orthogonal function; * P: precipitation; T: temperature; SST: sea surface temperature; ET: evapotranspiration; SMS: soil moisture; NDVI: normalized difference vegetation index; NLDAS: North American land data assimilation system; ENSO: El Niño and the Southern Oscillation; EALCO: Ecological Assimilation of Land and Climate Observation; CRU: Climatic Research Unit; ERA5L-TWSA: ERA5-land Derived TWSA; and CWSC: cumulative water storage change.

Basin-scale water balance calculations that combine rainfall, evapotranspiration, and runoff have also been used to reconstruct TWS_{GRACE} [79]. For example, Pan et al. [36] used this approach to reconstruct the TWS_{GRACE} over 32 global river basins using ground-based and remote sensing observations and LSM simulations from 1984 to 2006. Biases in rainfall and/or evapotranspiration estimates, in addition to the lack of runoff data availability, hinder the effectiveness of this approach. In addition, this technique does not take advantage of the full scope of information provided by the current TWS_{GRACE} record (e.g., anthropogenic and natural variabilities).

In recent years, data assimilation techniques have been increasingly used to reconstruct the TWS_{GRACE} , with higher spatial and temporal resolution. Assimilation techniques integrate TWS_{GRACE} with LSMs to enhance the model performance. For example, Eicker et al. [80] used an ensemble-based Kalman filter approach to assimilate TWS_{GRACE} into the Water Global Analysis and Prognosis (WaterGAP) LSM to predict TWS on both basin and grid scales over the United States. Assimilation of TWS_{GRACE} data into several LSMs was performed to improve the models' output, particularly the output of the TWS component [81–87]. The assimilation technique is useful to horizontally downscale coarse

resolution and vertically disaggregate TWS_{GRACE} data. However, because there is a mismatch in spatial and temporal resolution between TWS_{GRACE} and LSMs, and the error properties of the TWS_{GRACE} data are complex, the assimilation process requires complex algorithms that can be computationally extensive [88].

The statistical and data mining techniques correlate variabilities in TWS_{GRACE} with changes in different hydroclimatic and hydrologic variables such as precipitation, temperature, vegetation indices (e.g., normalized difference vegetation index [NDVI]), evapotranspiration, soil moisture, and Global Land Data Assimilation System (GLDAS)-derived TWS (TWS_{GLDAS}). These approaches offer an advantage over other methods because they facilitate the reconstruction of TWS_{GRACE} at basin or grid scales. The former approach averages relevant variables over a specific basin [31,35,38,89], whereas the latter generates these variables for each pixel (e.g., $1^\circ \times 1^\circ$) [30,48,66,70]. Examples of these techniques used include artificial neural network (ANN) [20,32,33,41,42,64], convolutional neural network (CNN) [68,74,75,78], deep neural network (DNN) [71], generalized linear model (GLM) [41], random forest (RF) [40,76,90], support vector machines (SVM) [41,90], multilinear regression (MLR) [20,25,34,68], extreme gradient boosting (XGB) [69,73,90], automated machine learning (AutoML) [42], autoregressive exogenous (ARX) and nonlinear autoregressive with exogenous (NARX) [32,37,39], linear statistical models [29,30,35,66,72,77], seasonal auto-regressive integrated moving average (ARIMA) with exogenous variables (SARIMA) [71], and general regression neural network (GRNN) [28].

Note each of these techniques has its own shortcomings. For example, they (1) were reported to be effective only for large-scale (area $>200,000 \text{ km}^2$) basins [91], (2) require knowledge of basin characteristics (e.g., percent forest cover, irrigated areas) that might not be available for all basins [91], (3) are restricted to specific areas such as those experiencing strong ocean–land–atmosphere interactions [29,92], (4) perform better when linear relationships were reported between model inputs and TWS_{GRACE} [20], and, (5) are less effective in reconstructing TWS_{GRACE} trends in hydrogeologic systems affected by anthropogenic activities [71]. Moreover, all of these approaches either (1) compare the performance of multiple models without pinpointing to the leader model for each basin or grid cell on a global scale, (2) select the leader model without providing a comprehensive comparison of different models' performance at each grid or basin on a global scale, or (3) pinpoint the leader model without discussing the model inputs that significantly control TWS_{GRACE} variability at each grid or basin. In addition, none of these models were used to fill the gap between GRACE and GRACE-FO missions globally on both basin and grid scales. This study offers innovative solutions to overcome the majority of these limitations. Globally, for both grid and basin scales, a leader model was defined as the model that combines the best (highest statistical performance during the testing phase) of the three models (GLM, GBM, and DNN). The relative importance of the leader model inputs was also provided.

3. Innovative Approach to Fill Gaps in TWS_{GRACE} Record

In this study, three different machine learning algorithms GLM, GBM, and DNN are used to fill the TWS_{GRACE} gaps globally, on both basin and grid (total grid points: 14,310) scales. Different types of algorithms were selected to better improve the fitting results of the TWS_{GRACE} data. Sixty-two major global river basins covering a wide range of climatic, hydrologic, and geologic settings were included in this study (Figure 1). Table A1 (Appendix A) lists the name, area, and climate setting of each of these basins. A comprehensive set of hydrological and climatic variables including rainfall, temperature, evapotranspiration, TWS_{GLDAS} , NDVI, ENSO climate index, and annual cycles derived from GRACE ($Annual_{GRACE}$) and GLDAS ($Annual_{GLDAS}$) were used as model inputs. These input variables were selected to best represent spatiotemporal variations in TWS_{GRACE} data globally [25,66,71]. The TWS_{GRACE} data represent the model output (target).

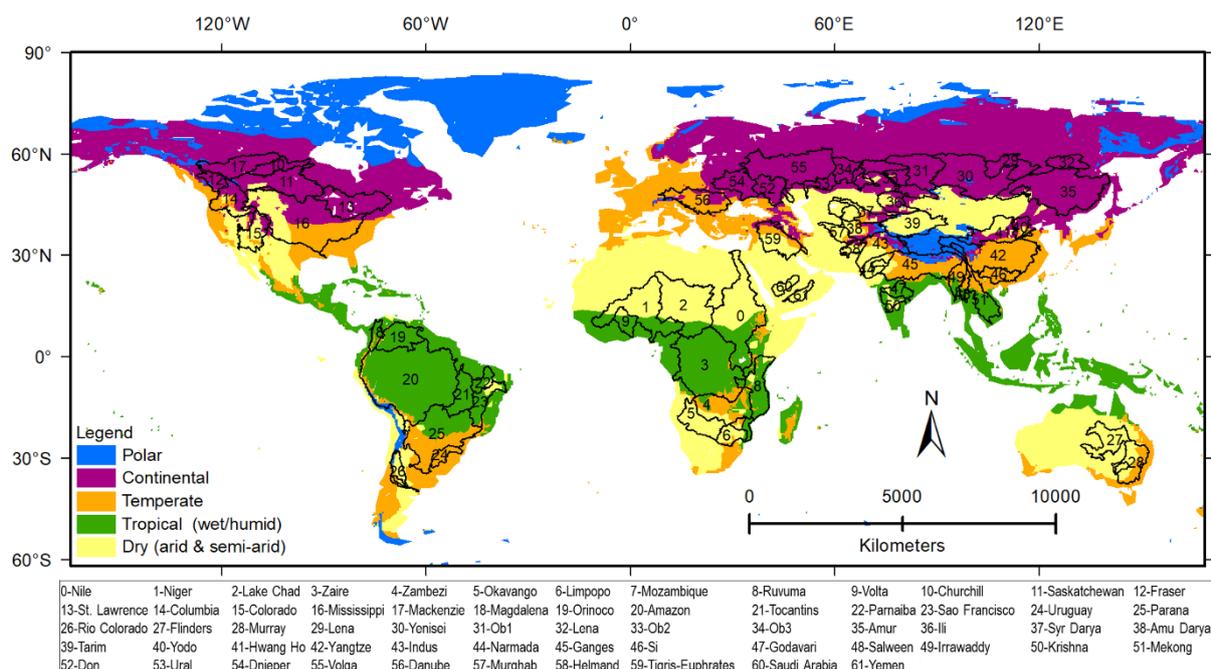


Figure 1. Spatial distribution of the 62 global watersheds (names are shown in the bottom) examined in this study. Also shown are the simplified Köppen–Geiger global climate zones [93].

The model inputs (e.g., rainfall, temperature, evapotranspiration, TWS_{GLDAS} , NDVI, ENSO, $Annual_{GRACE}$, and $Annual_{GLDAS}$) and target (e.g., TWS_{GRACE}) data were divided randomly into training (65%), validation (15%), and testing (20%) sets. Out of the available time series (April 2002–April 2020; 184 months), 147 months were randomly selected to train and validate the model, and 37 months were randomly selected to test the model performance. Random selection of the training and testing sets enables the designated algorithms to better understand, not memorize, the temporal variability in TWS_{GRACE} , hence leading to better predictions of TWS_{GRACE} gaps. The data gaps in the GRACE record (20 months), between GRACE and GRACE-FO (11 months), and in the GRACE-FO mission (2 months) were used as a forecasting (e.g., gap filling) set (total: 33 months).

The three models were compared based on their performances for the training, validation, and testing phases using various statistical parameters as presented in Section 3.3. To avoid overfitting for each model, the early stopping criteria were implemented using the mean square error (MSE) as a stopping metric, with stopping rounds of 5 and stopping tolerance of 0.0001. The selected leader model was the one that had the highest statistical performance during the testing phase of the three models (GLM, GBM, and DNN). In the following sections, a comprehensive description of each model and the details of the model input data and performance measures are presented.

3.1. Machine Learning Models

The GLM, GBM, and DNN machine learning models were used to quantify the relationship between model inputs, on the one hand, and the TWS_{GRACE} data, on the other hand. Each of these models represent a member of a machine learning family that has been extensively used to model a complex time series such as TWS_{GRACE} . Different model types were used to ensure the improvement of model fit with the actual TWS_{GRACE} data.

3.1.1. Generalized Linear Model (GLM)

The GLM is a flexible and extended form of the ordinary linear regression model and is represented by the following equation:

$$y_i = \beta_0 + \beta_i x_i + e_i, \quad (1)$$

where β_0 and β_i represent the intercept and the weight terms, respectively, and e_i is the Gaussian random variable, which is the error/noise in the model. The linear regression model assumes that y_i and error are normally distributed, and x_i has constant variance. In the GLM, the errors and y_i do not need to be normally distributed assuming a distribution from an exponential family, which allows variable variance and a nonlinear relationship between target and input variables [94]. The GLM uses absolute values of t-statistics to estimate the importance of a variable [95]. More details about GLMs can be found in Cox et al. [96].

3.1.2. Gradient Boosting Machine (GBM)

The GBM model is one of the most powerful supervised machine learning approaches, and it has already shown promising performance in both regression and classification problems [97]. The GBM is a tree-based improved stepwise additive boosting algorithm that sequentially fits new tree-based models [98] and reduces bias and variance by combining an ensemble of weak learners as a weighted sum. The model optimizes key hyperparameters (e.g., number of trees, depth of trees, and learning rate) and offers an optimal technique to handle unbalanced datasets [99]. The simplified equations for GBM are expressed as follows:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x), \quad (2)$$

$$\gamma_m = \operatorname{argmin}_{\gamma} \sum_{i=1}^n L(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)), \quad (3)$$

where $F_m(x)$ is the output, $L(y_i, F(x_i))$ is the loss function, γ_m is the residual, $h_m(x_i)$ is the base/weak learner, and x_i and y_i are the input and target variables, respectively. We set a varying learning rate from 0.01 to 0.1 with a 0.005 increment, sample rate from 0.1 to 1 with a 0.05 increment, maximum tree depth from 1 to 20, and number of maximum trees to 50. The model tries all possible combinations of these hyperparameters and reports the best training results. In the GBM, the variable importance is derived based on the knowledge of the variance on the input variables [100]. A more detailed description of the GBM model is presented in Friedman [98] and Friedman [97].

3.1.3. Deep Neural Network (DNN)

The DNN structure is complex compared to traditional ANNs, which allows the DNN to automatically extract deeper and more complicated relationships between model inputs and outputs [101]. The DNN is composed of interconnected organized layered neurons. The first layer of neurons is called the input node. It receives information from input data and combines and passes the data to the next layer through transformation. The last layer in the network is called the output layer and produces the output of the model. The layers between input and output are called hidden layer(s). The input–output relationship for each layer is given by this equation [102]:

$$y_i^j = \varnothing \left(M_{k=1}^{j-1} w_{ik}^{j-1} y_i^{j-1} + w_{i0}^{j-1} \right), i = 1, 2, \dots, J^k, \quad (4)$$

where j represents the layer index, y_i^{j-1} is the j th layer input with dimension M^{j-1} , J^k represents the number of hidden neurons used, w_{ik} are elements of the weight matrix, w_{i0} represents bias term in model, \varnothing is the activation function, and y_i^j is the model output. We set the number of hidden layers to 2 and 3 layers each with 200 neurons, activation function to rectifier, varying learning rate from 0 to 0.1 with a 0.001 increment, and input dropout ratio from 0.1 to 0.2 with a 0.05 increment. In DNN, the variable importance is derived from the weights of neurons between the input layers and hidden layers [103]. A more detailed description of the DNN model is presented by Bengio [104].

3.2. Input and Target Data

The model input data include eight variables (Figure 2) that combine remote sensing, hydrological, and climatic datasets (i.e., rainfall, temperature, evapotranspiration,

TWS_{GLDAS} , NDVI, ENSO, $Annual_{GRACE}$, and $Annual_{GLDAS}$). The model target data are represented by the TWS_{GRACE} . Input variables were reported to have controls on TWS_{GRACE} . For example, an increase in rainfall due to changes in ENSO will increase soil moisture (e.g., TWS_{GLDAS}), NDVI, and consequently TWS, whereas an increase in temperature will increase evaporation and decrease TWS [105–107]. A lag of 3 months was used for input time series to account for the reported lags between TWS_{GRACE} and the model inputs. The TWS_{GRACE} exhibits couple months lag given the time it takes for any hydrological system to respond to any spatiotemporal changes in rainfall and temperature [13,42,71,108].

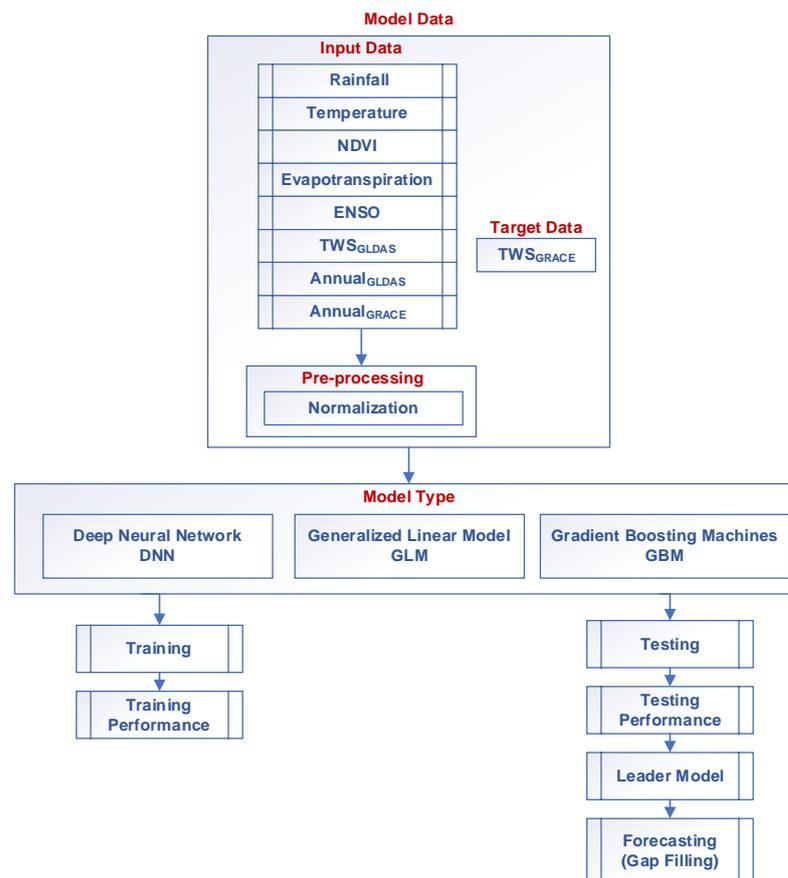


Figure 2. Flowchart showing model types, input data, and model structure used in this study.

The input and target variables were obtained from different sources with different grid size that range from 0.01° (1 km) to 1° (~110 km). For the grid-scale predictions, the model inputs and target variable were resampled at $1^\circ \times 1^\circ$ using the nearest neighbor resampling technique to make all variables comparable and also to make the TWS_{GRACE} reconstruction results comparable to the published ones. We generated a time series for each input (total: 8) and target (total: 1) variable at each grid cell (total: 14,310). For basin scale prediction, the raw input and target variables were averaged over each of the 62 investigated basins to generate a time series for each variable at the basin scale.

The input data were normalized between 0 to 1 using the following equation:

$$\bar{x}_i = \frac{x_i - x_{\min}}{x_{\max} - x_{\min}} \quad (5)$$

where \bar{x}_i is normalized value for x_i and x_{\min} and x_{\max} are minimum and maximum values for the time series.

The annual cycle for TWS_{GRACE} and TWS_{GLDAS} were calculated by simultaneously fitting trend and seasonal (e.g., annual and semiannual) terms to each time series according to the following equation:

$$S = a + b \cdot t + c \cdot \sin \omega t + d \cdot \cos \omega t + e \cdot \sin 2\omega t + f \cdot \cos 2\omega t \quad (6)$$

where S is TWS_{GRACE} or TWS_{GLDAS} time series, a is the offset, b is the long-term trend, c and d are annual terms, e and f are semi-annual terms, t is the time vector, and $\omega = 2\pi/T$ with T defined as the annual period.

3.2.1. GRACE-Derived TWS (TWS_{GRACE})

The latest version of GRACE mass concentration (mascon) products (RL06M) provided by the Jet Propulsion Laboratory (JPL) was used in this study. The JPL-RL06M data are available at <https://grace.jpl.nasa.gov> (accessed on 10 December 2021) on a $0.5^\circ \times 0.5^\circ$ grid scale; however, the native resolution is $3^\circ \times 3^\circ$ equal-area caps [109]. The TWS_{GRACE} product (expressed in equivalent water thickness) for the April 2002 to April 2020 period was used in this study as the target data. Standard postprocessing procedures were applied to TWS_{GRACE} data, including replacement of the C20 coefficient, addition of geocenter motion, and removal of solid Earth effects, such as glacial isostatic adjustments. The scaling factor was applied to reduce the leakage error [110]. The JPL-RL06M solutions were selected because they are superior to spherical harmonic solutions in both accuracy and reconstruction results as reported by several studies [71,111]. In addition, leakage error in the JPL-RL06M solutions can be readily assessed and minimized using scale factors [110].

3.2.2. GLDAS-Derived TWS (TWS_{GLDAS})

Two significant terrestrial storage components are missing in the GLDAS simulations, the groundwater and surface water bodies. Despite the limitation of using the GLDAS model alone to reconstruct TWS_{GRACE} , in this study TWS_{GLDAS} is integrated with other input variables to maximize the accuracy of the reconstructed TWS_{GRACE} data. The GLDAS model uses sophisticated algorithms combined with ground-based observations to produce enhanced fields of land surface states and fluxes [112]. The TWS_{GLDAS} data from the GLDAS NOAH model [113] was used in this study because it shows a better correlation with TWS_{GRACE} on the global scale compared to other models (i.e., CLM, Mosaic, and VIC) [33,71,114]. In the NOAH version, the TWS_{GLDAS} is the sum of soil moisture, plant canopy water storage, and accumulated snow. The monthly TWS_{GLDAS} data are available at a spatial resolution of $0.25^\circ \times 0.25^\circ$ (<https://disc.gsfc.nasa.gov/datasets>) (accessed on 10 December 2021).

3.2.3. Rainfall

Rainfall data were extracted from the Integrated Multi-satellite Retrievals for Global Precipitation Measurement (IMERG) product of the Global Precipitation Measurement (GPM) mission, which provides a half-hourly and monthly precipitation product on a $0.1^\circ \times 0.1^\circ$ grid scale over the globe [115]. IMERG merges and interpolates satellite precipitation data with rain gauge estimates to produce high-resolution rainfall products [116]. Compared to other remote sensing-derived rainfall products, GPM provides better accuracy, improved sampling, and is able to capture the intermittency of precipitation in majority of climatic and hydrologic zones [117]. IMERG data are available from https://disc.gsfc.nasa.gov/datasets/GPM_3IMERGM_06/ (accessed on 10 December 2021).

3.2.4. Temperature

Air temperature data were retrieved from the European Centre for Medium-Range Weather Forecasts (ECMWF) Re-Analysis (ERA5-Land) project. The fifth-generation ECMWF reanalysis for global climate, ERA5, replaces the ERA-Interim reanalysis. ERA5-Land was produced by replaying the land component of the ECMWF ERA5 climate reanalysis. Data are available at a temporal resolution of 1 h and a spatial resolution of $0.1^\circ \times 0.1^\circ$ [118] from <https://cds.climate.copernicus.eu/cdsapp#!/dataset/reanalysis-era5-land-monthly-means?tab=form> (accessed on 10 December 2021).

3.2.5. Evapotranspiration

The Moderate Resolution Imaging Spectroradiometer (MODIS) derived MOD16 (Collection 6 Version 2) global evapotranspiration products, used in this study, are the first regular 1 km² land surface evapotranspiration datasets that are provided at 8-day, monthly, and annual temporal resolutions [119]. MOD16 evapotranspiration is derived based on the Penman–Monteith equation using daily meteorological reanalysis data and 8-day remotely sensed vegetation property dynamics from MODIS inputs. The MODIS evapotranspiration data are available at <http://www.ntsg.umt.edu/project/mod16#data-product> (accessed on 5 December 2021).

3.2.6. Normalized Difference Vegetation Index (NDVI)

The NDVI data used in this study are generated from averaged level-3 MODIS Terra (MOD13C2) and MODIS Aqua (MYD13C2) products (available at https://lpdaac.usgs.gov/dataset_discovery/modis/modis_products_table) (accessed on 5 December 2021). Both MOD13C2 and MYD13C2 are global monthly datasets with spatial sampling resolution of 0.05° [120].

3.2.7. Climate Indices

The Monthly multivariate ENSO Index (MEI), available at <https://www.esrl.noaa.gov/psd/enso/mei/index.html> (accessed on 15 December 2021), is calculated based on six main variables (sea-level pressure, zonal and meridional components of the surface wind, sea surface temperature, surface air temperature, and total cloudiness fraction of the sky) over the tropical Pacific.

3.3. Performance Measures

Model performance, for both grid and basin simulations, was evaluated during training and testing phases using the normalized root-mean-square error (NRMSE), Pearson's correlation coefficient (CC), and Nash–Sutcliffe efficiency coefficient (NSE). We reported the average value \pm one standard deviation for each of these measures.

The NRMSE (Equation (7)) is the root-mean-square error normalized by standard deviation of the observation data with value ranges from 0 to ∞ :

$$\text{NRMSE} = \frac{1}{\sigma} \sqrt{\frac{\sum_{i=1}^n (y_i - x_i)^2}{n}} \quad (7)$$

The CC (Equation (8)) measures the strength of linear associations between predicted and actual data with value ranges between -1 and 1 . A CC value of zero (0) means there is no correlation, and positive (negative) values mean positively (negatively) correlated, with 1 (-1) indicating perfect positive (negative) correlations between predicted and observed values:

$$\text{CC} = \frac{\sum_{i=1}^n (y_i - \hat{y})(x_i - \hat{x})}{\sqrt{\sum_{i=1}^n (y_i - \hat{y})^2} \sqrt{\sum_{i=1}^n (x_i - \hat{x})^2}} \quad (8)$$

The normalized statistical coefficient NSE (Equation (9)) measures the relative magnitude of residual variance to the variance of actual/measured data [121]. The NSE values range from $-\infty$ to 1 with optimal performance at 1 :

$$\text{NSE} = 1 - \frac{\sum_{i=1}^n (y_i - x_i)^2}{\sum_{i=1}^n (x_i - \hat{x})^2} \quad (9)$$

where x and y represent actual and predicted time series; \hat{x} and \hat{y} represent average of x and y ; n is the number of data used in testing; and σ is the standard deviation of the time series.

In this study, the model performance is classified into four main categories [103,122]: (a) very good performance if $\text{NSE} > 0.7$, $\text{CC} > 0.8$, and $\text{NRMSE} < 0.5$; (b) good performance if $\text{NSE} > 0.6$, $\text{CC} > 0.7$, and $\text{NRMSE} < 0.6$; (c) satisfactory performance if $\text{NSE} > 0.5$, $\text{CC} > 0.6$, and $\text{NRMSE} < 0.7$; and (d) poor performance if $\text{NSE} < 0.5$, $\text{CC} < 0.6$, and $\text{NRMSE} > 0.7$.

4. Results

4.1. Model Performance: Grid Scale

Figure 3 shows the spatial distribution of the performance metrics (i.e., NSE, CC, NRMSE) of three models (i.e., GLM, GBM, and DNN) during the testing phase. The average testing performance matrices for grid and basin scales are shown in Table 2. The training performance is shown in Figure A1 (Appendix A). Figure 3 also shows the frequency distribution of each performance metric. Examination of Figure 3 indicates that all models show similar overall patterns of testing performance. Overall, the GLM testing performance has average NSE, CC, and NRMSE values of 0.55 ± 0.26 , 0.74 ± 0.19 , and 0.63 ± 0.19 , respectively (Figure 3a–c, and Table 2). Among the investigated grids (total: 14,310), the GLM shows a very good performance for 29%, good performance for 19%, satisfactory performance for 17%, and poor performance for 35% of the grid cells (Figure 4a). The GBM average performance values for the NSE, CC, and NRMSE are estimated to be 0.59 ± 0.23 , 0.77 ± 0.15 , and 0.61 ± 0.17 , respectively (Figure 3d–f, and Table 2). The GBM model performance is very good, good, satisfactory, and poor for 31%, 22%, 18%, and 29% of total grid cells, respectively (Figure 4a). Overall, the average performance of DNNs were lower than those of the GLMs and GBMs with average NSE, CC, and NRMSE values of 0.49 ± 0.28 , 0.73 ± 0.19 , and 0.68 ± 0.19 , respectively (Figure 3g–i, and Table 2). The DNN model performance is very good for 21%, good for 18%, satisfactory for 27%, and poor for 44% of the total investigated grids (Figure 4a).

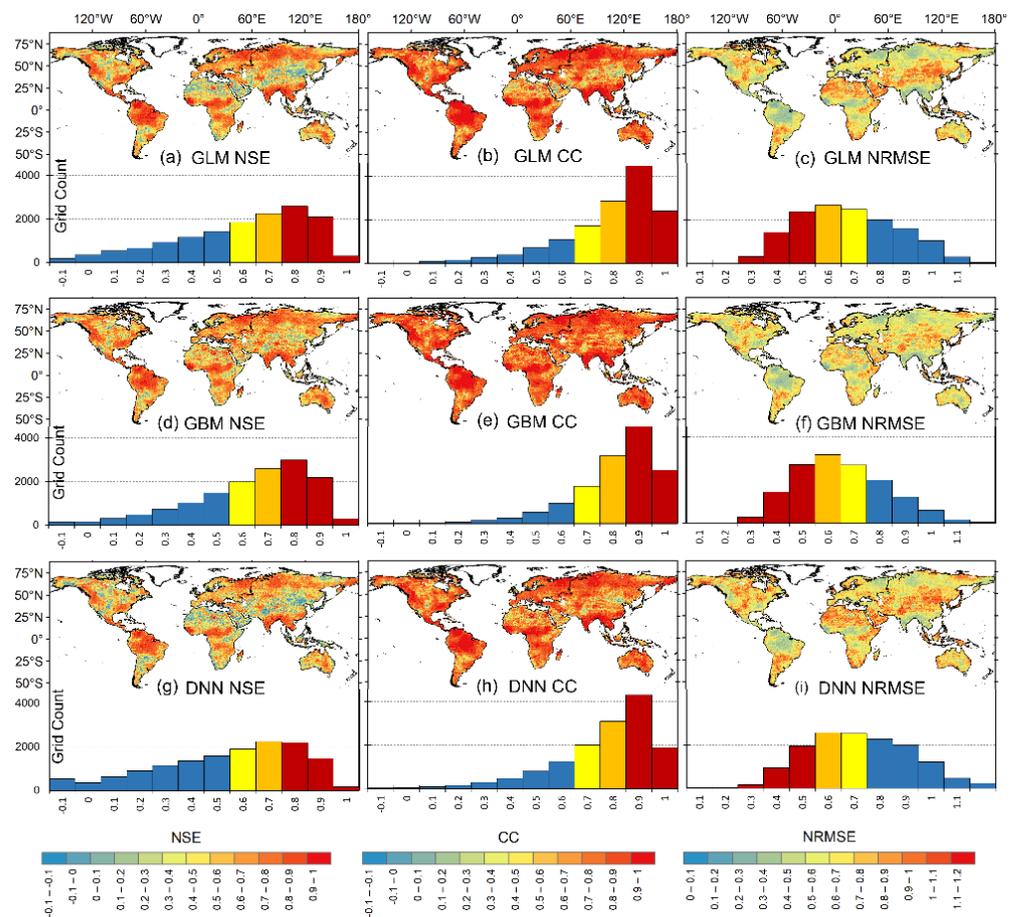


Figure 3. Spatial (maps) and frequency (bar plots) distributions of the grid-scale testing performance for the (a–c) GLMs, (d–f) GBM models, and (g–i) DNN models. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

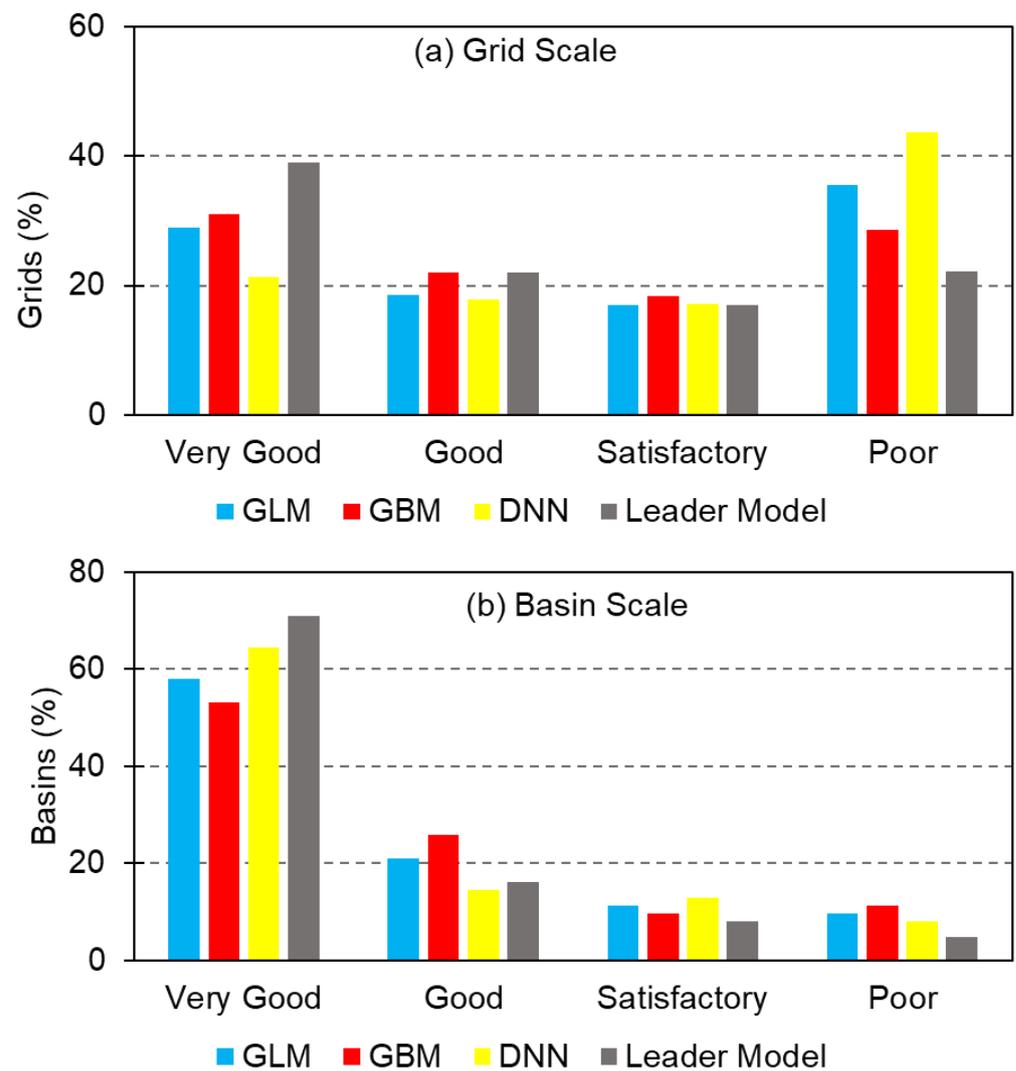


Figure 4. Frequency distribution of (a) grid-scale and (b) basin-scale testing performance for the GLMs, GBM models, DNN models, and leader models.

Table 2. The average testing performance matrices for grid and basin scales.

Grid Scale				
	GLM	GBM	DNN	Leader Model
NSE	0.55 ± 0.26	0.59 ± 0.23	0.49 ± 0.28	0.65 ± 0.20
CC	0.74 ± 0.19	0.77 ± 0.15	0.73 ± 0.19	0.81 ± 0.13
NRMSE	0.63 ± 0.19	0.61 ± 0.17	0.68 ± 0.19	0.56 ± 0.16
Basin Scale				
	GLM	GBM	DNN	Leader Model
NSE	0.74 ± 0.15	0.73 ± 0.17	0.75 ± 0.17	0.78 ± 0.14
CC	0.87 ± 0.09	0.85 ± 0.11	0.88 ± 0.09	0.89 ± 0.07
NRMSE	0.48 ± 0.15	0.49 ± 0.16	0.46 ± 0.16	0.43 ± 0.14

Model performance was found to vary spatially. As indicated by the higher NSE testing values, all models have relatively better performance in relatively wet/humid regions such as the Amazon, South Asia, Central Africa, Southeastern United States, and Eastern Europe (Figures 1 and 3a,d,g). The CC and NRMSE for all models also show a

similar spatial pattern, with better performance in humid regions (Figures 1 and 3b,c,e,f,h,i). On the other hand, the performance of all models is relatively poor in arid, semi-arid, and highly irrigated regions (Figures 1 and A3). Lower NSE and CC and higher NRMSE values are found to be concentrated over the Sahara Desert, Arabian Peninsula, Northwest China, and the southern part of South America (Figure 3).

The input variables were found to have different impacts on model performance in different grids. We conducted a sensitivity analysis by evaluating the contribution of each input variable to the model performance. The spatial distribution of variables that are the most important is shown in Figure 5. The TWS_{GLDAS} was found to be the most important variable in 45%, 64%, and 39% of all grid points simulated by the GLMs, GBM, and DNN models, respectively. The second and third-most important variables were $Annual_{GRACE}$ (24%) and NDVI (13%), respectively, for the GLM; NDVI (12%) and temperature (9%), respectively, for the GBM; and temperature (16%) and rainfall (11%), respectively, for the DNN.

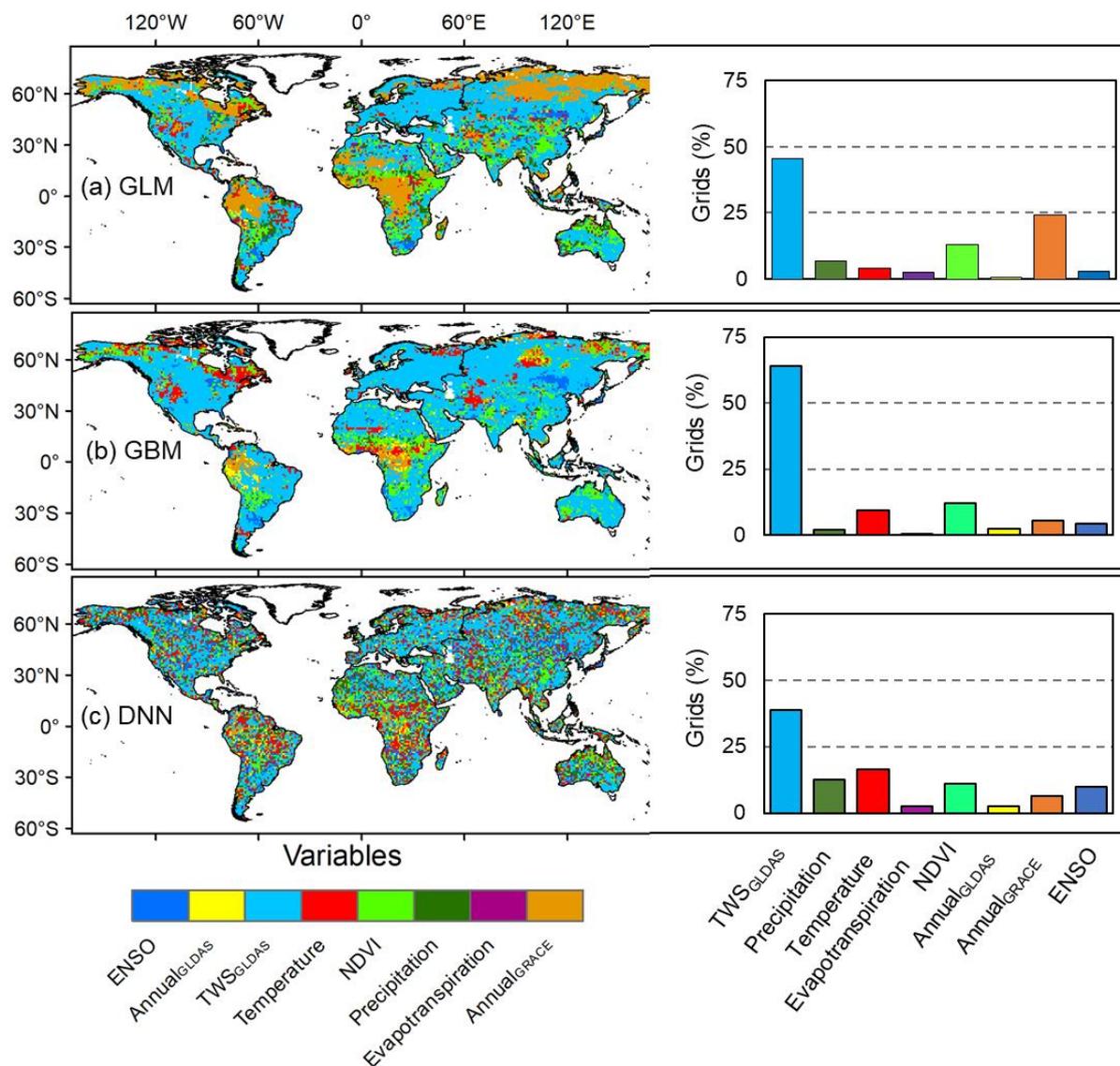


Figure 5. Spatial (left) and frequency (right) distribution of the grid-scale variable importance for (a) GLMs, (b) GBM models, and (c) DNN models.

Because model performance varies by grid location (Figure 3), a leader model (e.g., the best of the three models) was selected for each grid based on the best NSE value for

testing results (Figure 6a). The GBM model was the leader for 47% of the examined grid cells, whereas the GLM and DNN were the leaders for 36% and 17%, respectively. The leader model performance average NSE, CC, and NRMSE are 0.65 ± 0.20 , 0.81 ± 0.13 , and 0.56 ± 0.16 , respectively (Figure 6b–d, and Table 2).

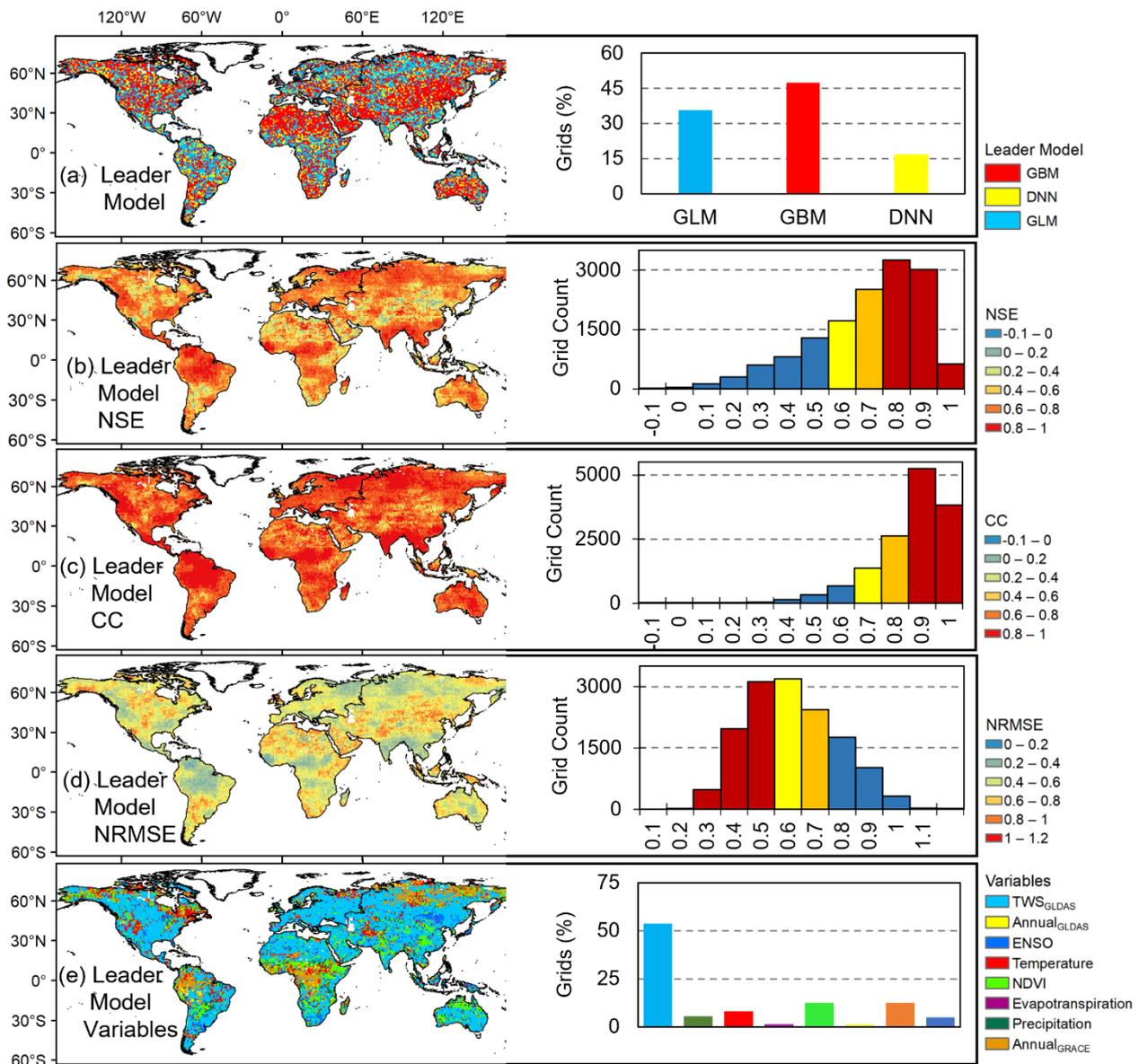


Figure 6. Spatial (left) and frequency (right) distributions of the grid-scale leader model (a) types, (b) testing NSE, (c) testing CC, (d), testing NRMSE, and (e) variable importance. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

The performance of the leader model is very good for 39%, good for 22%, satisfactory for 17%, and poor for 22% of the total investigated grids (Figure 4a). The leader model performance is significantly higher than that of any of the three individual models, particularly in the very good and poor classes (Figure 4a). In addition, the top three most important input variables for the leader model in each grid were found to be TWS_{GLDAS} (54%), Annual_{GRACE} (12%), and NDVI (12%) (Figure 6e).

4.2. Model Performance: Basin Scale

Figures 7 and A2 show the spatial distribution of the performance metrics over these 62 global watersheds during the testing and training phases, respectively. For the GLM, the average testing performance is estimated to be 0.74 ± 0.15 , 0.87 ± 0.09 , and 0.48 ± 0.15 for the NSE, CC, and NRMSE, respectively (Figure 7a–c, and Table 2). The GLM performance is very good for 58% of the basins (Figure 4b), particularly the Amazon, Godavari, Orinoco, Columbia, Irrawaddy, Tocantins, Salween, Irrawaddy, Krishna, and Mekong basins (e.g., Amazon: NSE = 0.95, CC = 0.98, NRMSE = 0.22) and good for 21%, satisfactory for 11%, and poor for 10% of the investigated basins (e.g., Saudi Arabia [NSE = 0.37, CC = 0.78, NRMSE = 0.62], Tarim, Yodo, Hwang Ho, Helmand, and Yemen; Figure 7a–c).

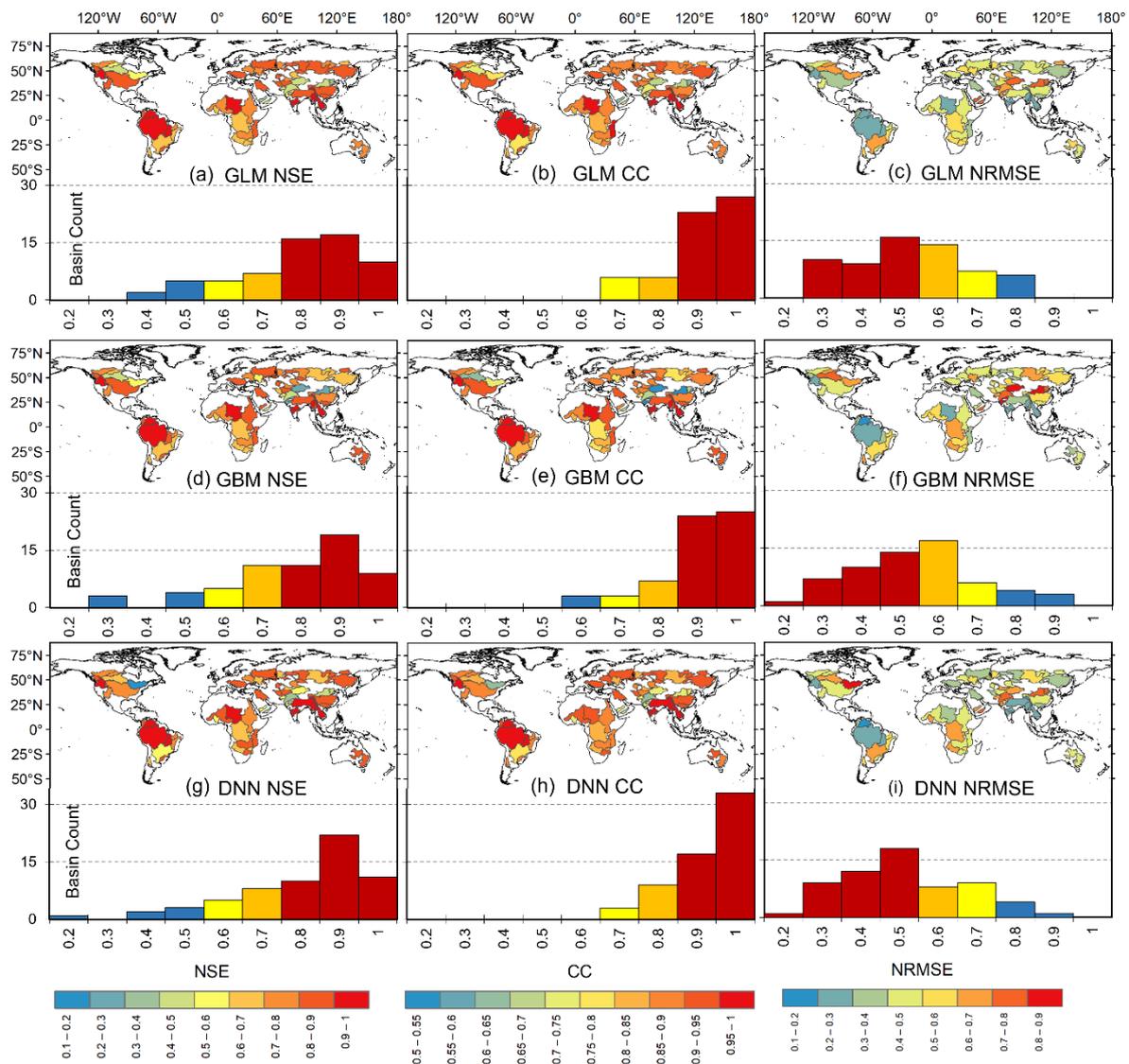


Figure 7. Spatial and frequency (bar plot) distribution of the basin-scale testing performance for the (a–c) GLM, (d–f) GBM, and (g–i) DNN models. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

The GBM model's general performance is estimated to be NSE = 0.73 ± 0.17 , CC = 0.85 ± 0.11 , NRMSE = 0.49 ± 0.16 (Figure 7d–f, and Table 2). The performance of GBM is very good for 53% of the investigated basins (e.g., Orinoco [NSE = 0.96, CC = 0.98, NRMSE = 0.19], Lake Chad, Columbia, Amazon, Godavari, Mekong, Don, and Ural), good for 26%, and satisfactory for 10% of the investigated basins (Figure 4b). The performance

of GBM, however, is poor for 11% of the basins, including Tarim (NSE = 0.25, CC = 0.5, NRMSE = 0.86), Yodo, Hwang Ho, Indus, Narmada, and Yemen. The DNN's model average performance was estimated to be 0.75 ± 0.17 , 0.88 ± 0.09 , and 0.46 ± 0.16 for NSE, CC, and NRMSE, respectively (Figure 7g–i and Table 2). The DNN model performance is very good for 65%, good for 14%, satisfactory for 13%, and poor for 8% of the investigated basins (Figure 4b). In particular, the performance of DNN is very good for basins such as Orinoco (NSE = 0.97, CC = 0.99, NRMSE = 0.17), Columbia, Amazon, Tocantins, Ganges-Brahmaputra, Godavari, Si, Irrawaddy, and Mekong and poor for the St. Lawrence (NSE = 0.19, CC = 0.63, NRMSE = 0.89), Yodo, Hwang Ho, Indus, and Yemen basins.

For all three models, TWS_{GLDAS} is the most important variable for most basins (Figure 8). Out of the 62 basins, TWS_{GLDAS} was the most important variable for 58%, 66%, and 52% of the basins for the GLMs (Figure 8a), GBM models (Figure 8b), and DNN models (Figure 8c), respectively. Of all the basins, the NDVI is the second-most important variable for 21% for GLMs, 16% for GBM models, and 23% for DNN models, respectively. Precipitation is the third-most important variable for the GLMs and DNN models with 10% and 8% of the basins, respectively, while $Annual_{GRACE}$ for the GBM (6% basins).

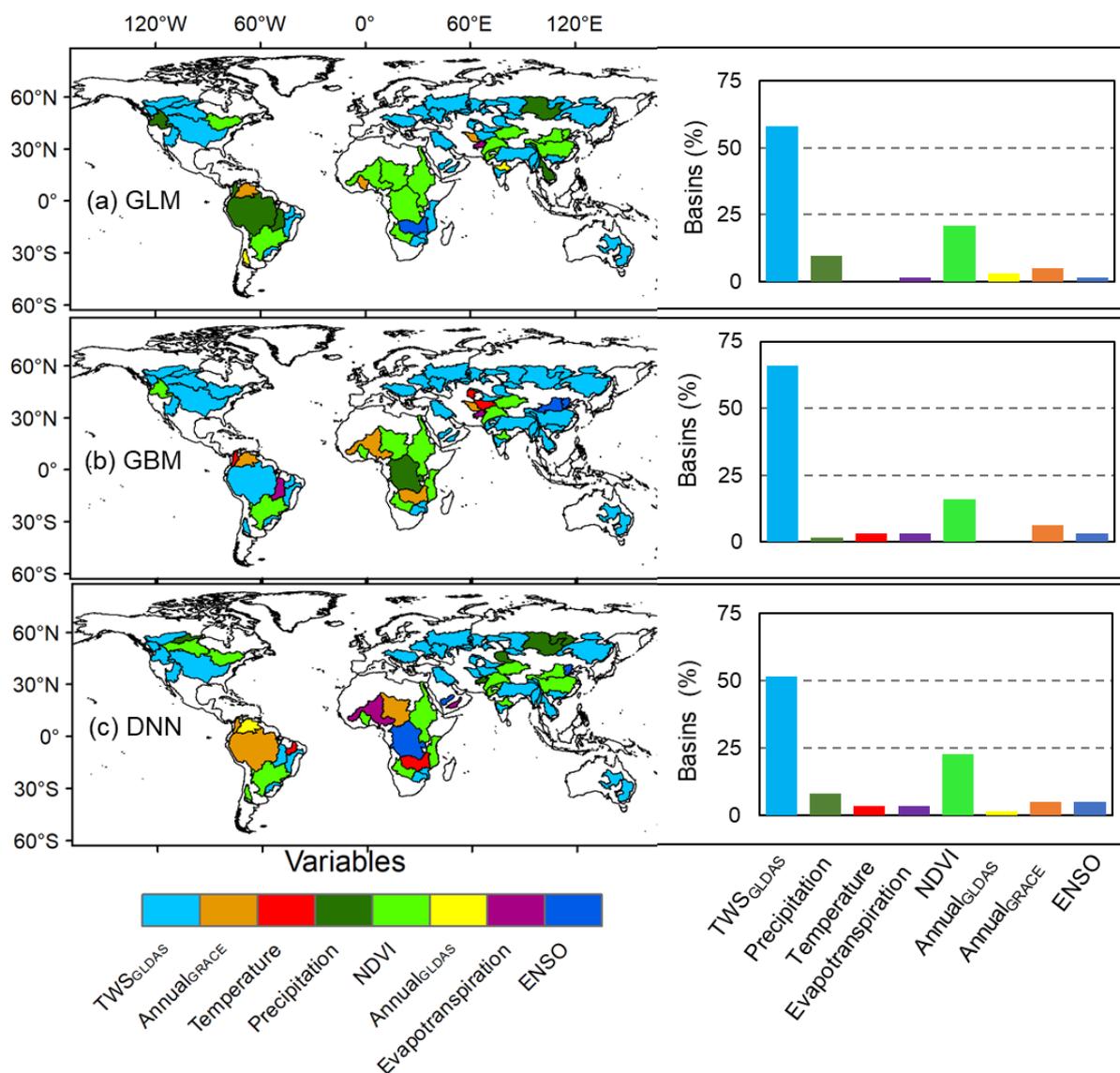


Figure 8. Spatial (left) and frequency (right) distribution of the basin-scale variable importance for (a) GLM, (b) GBM, and (c) DNN models.

Based on the testing performance measures, the DNN model outperforms the GBM and GLM models in most of the examined basins (Figure 9a). Thus, it is selected as a leader model for 31 (50%) of the investigated basins. On the other hand, the GBM and GLM are the leader models in 14 (23%) and 17 (27%) basins, respectively. The leader model's performance is significantly higher than that of any of the individual models. The leader model average performance NSE, CC, and NRMSE values are 0.78 ± 0.14 , 0.89 ± 0.07 , and 0.43 ± 0.14 , respectively (Figure 9b–d). Overall, the performance of the leader model is very good, good, satisfactory, and poor for 71%, 16%, 8%, and 5% of the investigated basins, respectively (Figure 4b). Overall, TWS_{GLDAS} , NDVI, and precipitation are the most important variables for 58%, 21%, and 10% of the basins simulated by the leader model, respectively (Figure 9e).

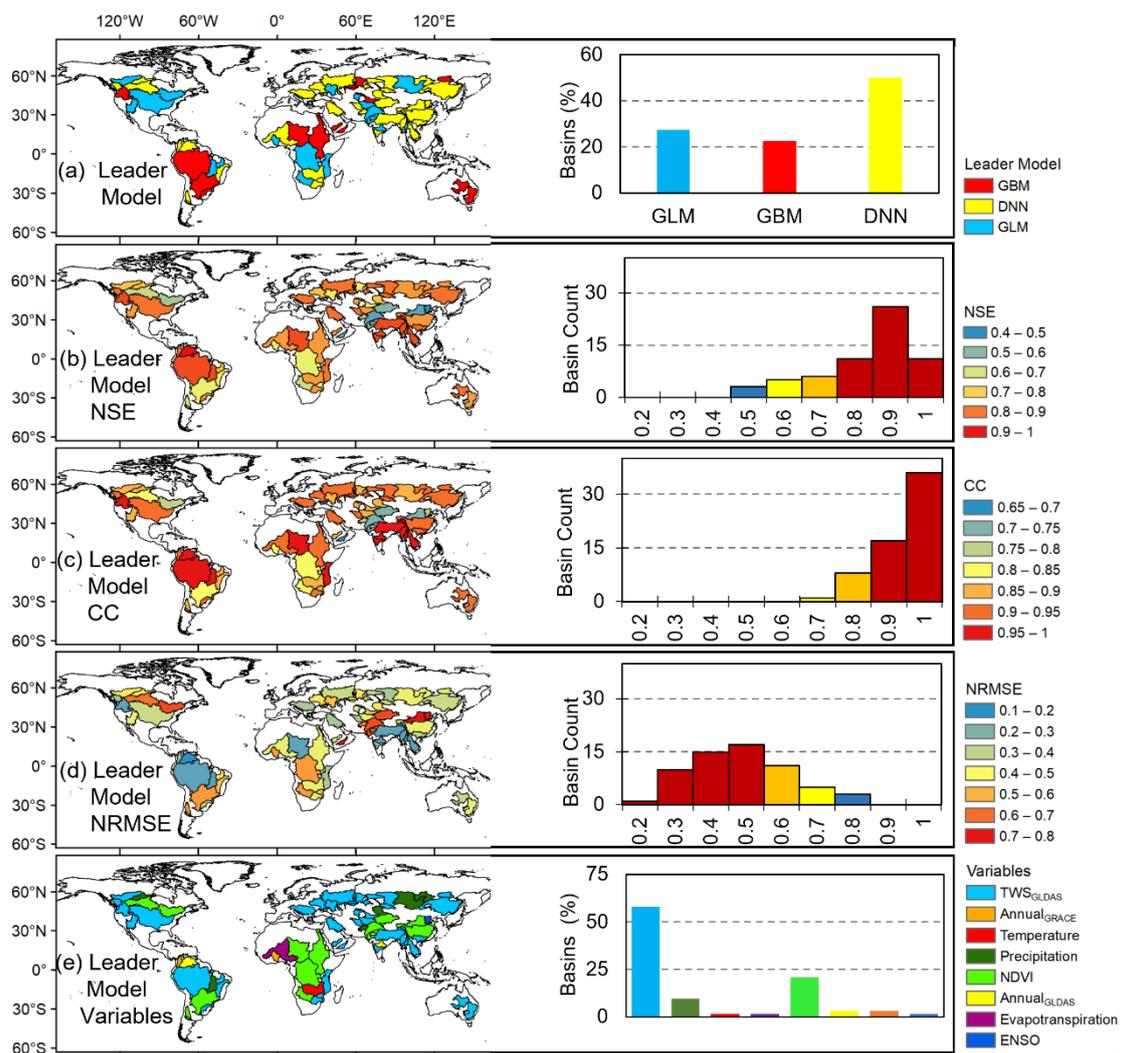


Figure 9. Spatial (left) and frequency (right) distribution of the basin-scale leader model (a) types, (b) testing NSE, (c) testing CC, (d) testing NRMSE, and (e) variable importance. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

4.3. TWS_{GRACE} Reconstruction Results

To evaluate the TWS_{GRACE} reconstruction results, eight basins were selected as representative examples of different climatic and hydrologic settings across the globe (Figure 10). The TWS_{GRACE} time series derived from the leader model is shown during training, testing, and forecasting (e.g., gap filling) phases. The root-mean-square error for testing phase was

plotted as an error bar for the reconstructed TWS_{GRACE} time series. The leader model did an excellent job of reconstructing the TWS_{GRACE} data. Inspection of Figure 10 reveals a better match of the reconstructed TWS_{GRACE} with the actual TWS_{GRACE} compared to that between actual TWS_{GRACE} and TWS_{GLDAS} . The NSE values between the reconstructed and the actual TWS_{GRACE} records are higher (minimum: 0.93; maximum: 0.98) compared to those between TWS_{GLDAS} and actual TWS_{GRACE} records (minimum: 0.45; maximum: 0.85). Figure A4 (Appendix A) shows higher NSE values between the reconstructed and the actual TWS_{GRACE} records compared to those between TWS_{GLDAS} and actual TWS_{GRACE} records for all of the examined 62 basins. The leader model was able to learn and capture the biases between the TWS_{GRACE} and TWS_{GLDAS} . In addition, the leader model accurately captured seasonal variations in TWS_{GRACE} in each of the investigated basins.

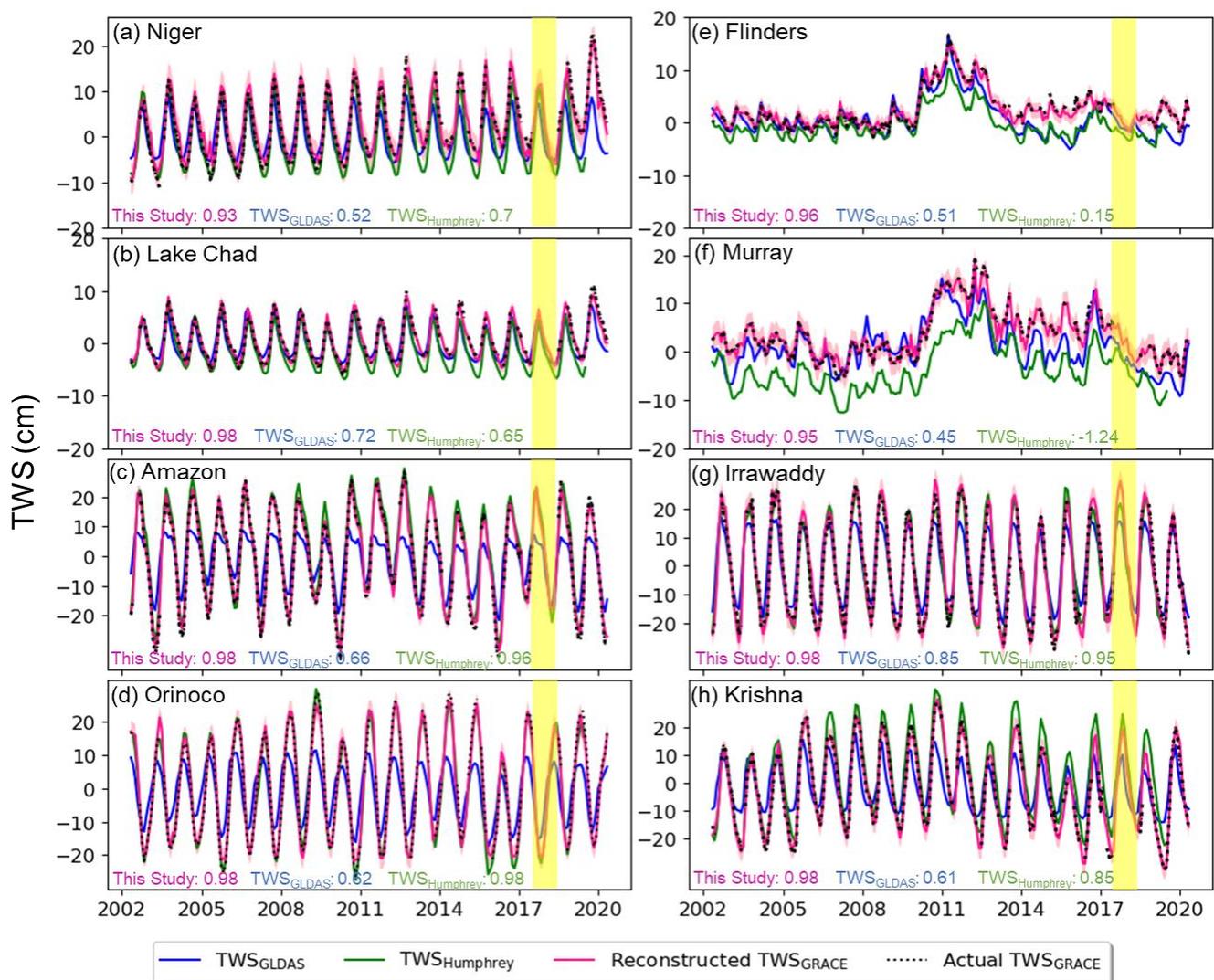


Figure 10. Reconstructed TWS_{GRACE} results for eight representative basins: (a) Niger, (b) Lake Chad, (c) Amazon, (d) Orinoco, (e) Flinders, (f) Murray, (g) Irrawaddy, and (h) Krishna. The actual TWS_{GRACE} , reconstructed TWS_{GRACE} , TWS_{GLDAS} , and Humphrey and Gudmundsson (2019)-derived TWS ($TWS_{Humphrey}$) time series are indicated by black dots, pink line, blue line, and green lines, respectively. The root-mean-square error for the testing set is plotted as error bar (pink shading) for the reconstructed TWS_{GRACE} . The vertical yellow rectangle shows the gap period between the GRACE and GRACE-FO missions. The NSE between the actual TWS_{GRACE} and reconstructed TWS_{GRACE} , the actual TWS_{GRACE} and TWS_{GLDAS} , and actual TWS_{GRACE} and $TWS_{Humphrey}$ are shown at the bottom of each subplot in pink, blue, and green text, respectively.

Comparison of this study's reconstructed TWS_{GRACE} results and those produced by Humphrey and Gudmundsson [66] ($TWS_{Humphrey}$; Figure 10) indicate a better agreement with the observed TWS_{GRACE} of the former. The current study's reported NSE values between the reconstructed and actual TWS_{GRACE} records are higher (minimum: 0.93; maximum: 0.98) than those derived by $TWS_{Humphrey}$ and actual TWS_{GRACE} records (minimum: -1.24 ; maximum: 0.98). The same pattern is observed over the entire 62 basins (Figure A4) revealing the improved performance by this study's approach at reconstructing the TWS_{GRACE} trends that are missing from that generated by $TWS_{Humphrey}$.

Inspection of the reconstructed TWS_{GRACE} data during the gap period (July 2017–May 2018) indicates that the grid-scale reconstructed TWS_{GRACE} was also able to capture the August–September high (Figure 11b,c) and the April–May low (Figure 11j,k) TWS_{GRACE} records in South Asia and Central Africa. The April–May high (Figure 11j,k) and October–November low (Figure 11d,e) TWS_{GRACE} records in the Amazon region are also well represented. Furthermore, the reconstructed TWS_{GRACE} reveals a clear response to many climate extremes that occurred during the data gap period. For example, the 2018 Australian drought [123] was captured at both the basin scale (Flinders and Murray basins; Figure 10e,f) and the grid scale (Figure 11l) reconstructed TWS_{GRACE} . Figure 11l shows reconstructed TWS_{GRACE} data over Australia during September 2017 (top left corner) and September 2018 (bottom left corner); the reconstructed TWS_{GRACE} record was lower in 2018 compared to 2017. In the United States, the hurricane season was extremely active in 2017, with four category-three or higher hurricanes that made landfall [124]. The reconstructed TWS_{GRACE} captures the effects of Hurricanes Harvey and Irma (August–September 2017, in the Gulf of Mexico coastal area; Figure 11l), as indicated by the higher TWS_{GRACE} record observed during September 2017 compared to that observed in September 2018.

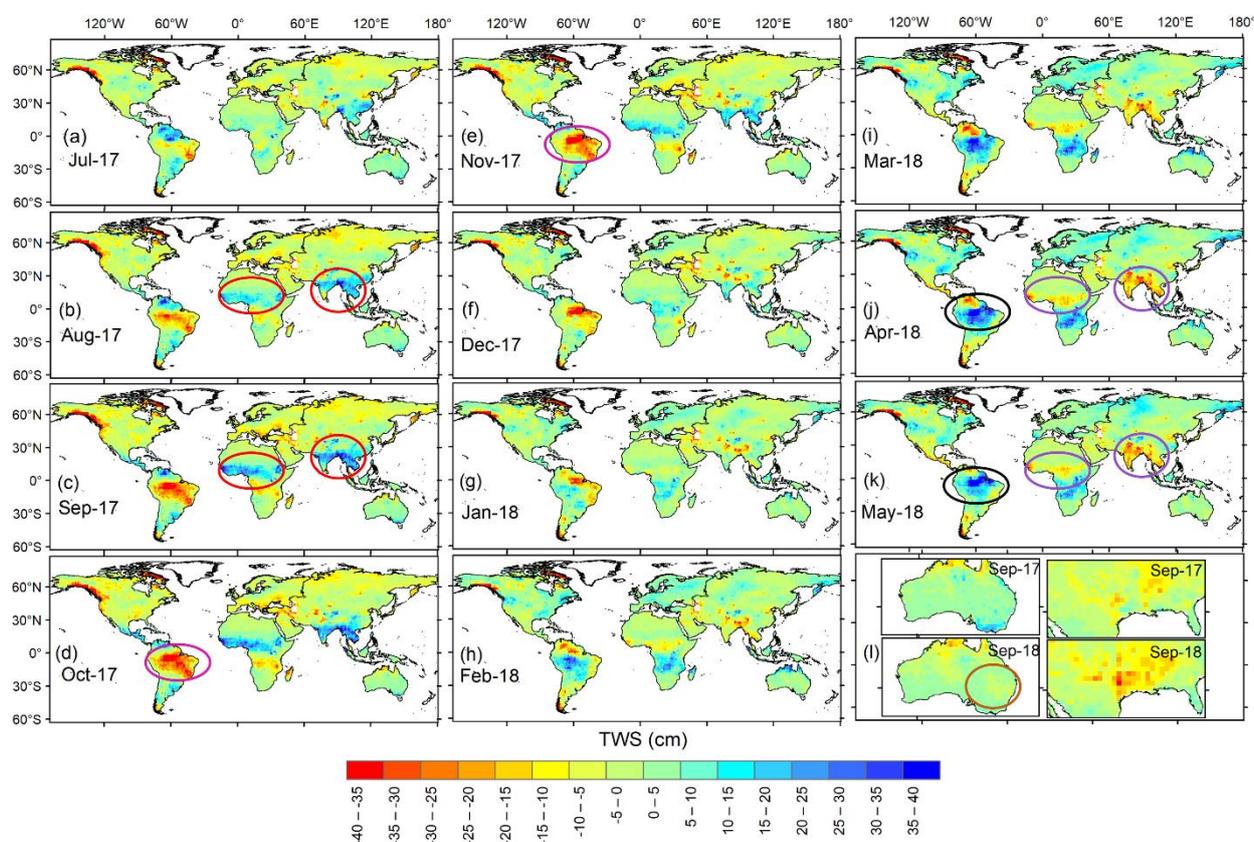


Figure 11. Global monthly (August 2017–May 2018; (a–k)) grid-scale reconstructed TWS_{GRACE} data for the gap period between GRACE and GRACE-FO missions. The circles depict the regions where the reconstructed TWS_{GRACE} captures the strong seasonal variations and extreme events [i.e., August–September high (red), April–May low (purple), April–May high (black), and October–November low

(pink)]. The reconstructed TWS_{GRACE} data over Australia for September 2017 (panel (I); top left corner) and September 2018 (panel (I); bottom left corner) are also shown. The United States' extreme active hurricane season 2017 is compared with 2018 in Figure 111 (right panel).

5. Discussion

The employed models (GLM, GBM, and DNN) perform well in the majority of the investigated basins and grid cells. However, no single model performed exceptionally everywhere. The three models show similar spatial patterns in their performance. Similarity in the spatial variability of all models' (e.g., GLM, GBM, and DNN) performance during both training and testing phases might be related to the use of a larger set of model inputs. The discrepancies in the performance measures between different models, as indicated by relatively small ranges of NSE, CC, and NRMSE, are expected because these models have different theories, algorithms, assumptions, and principals. The GLM is a standard linear regression model; the DNN and GBM, however, model the nonlinear relationship between the model's target and inputs. The difference in performance between nonlinear models might also be due to the size of the training and testing sets.

All models indicated a slightly lower performance during the testing phase than in the training phase. The relatively small decline in testing performance may be due to the relatively short number of the training samples [42]. In this study only 147 monthly TWS_{GRACE} values were used in the training phase. An additional reason for differences in performance between the training and testing phases could be the diverse temporal patterns in the model inputs and target variables in the testing phase compared to those in the training phase since data points for these phases were selected randomly.

All models show a relatively better (i.e., high NSE, high CC, and low NRMSE) performance in wet regions on both grid (e.g., Amazon region and surroundings, Indochina Peninsula, Central Africa, and the East European Plain) and basin (e.g., Lake Chad, Orinoco, Amazon, Tocantins, Godavari, Salween, Irrawaddy, Krishna, and Mekong) scales. This higher performance can be attributed mainly to the fact that the spatiotemporal variability in TWS_{GRACE} in these regions is controlled mainly by natural interventions. These interventions are well captured in the model input variables (e.g., rainfall, temperature). In addition, the TWS_{GRACE} data show higher signal-to-noise ratios in humid areas.

The three models performed poorly in arid and semi-arid regions such as North Africa, the Arabian Peninsula, and Northwest China at both grid and basin (e.g., basins Tarim, Yodo, Hwang Ho, Indus, Narmada, Yemen, and Saudi Arabia) scales. Anthropogenic activities such as groundwater extraction for irrigation purposes (Figure A3) are known to occur in these regions [125,126]. In these regions the anthropogenic component is expected to represent a larger percentage of the total TWS_{GRACE} when compared to humid/wet areas. None of the model input variables have accounted for the significant impacts of anthropogenic activities (e.g., lowering of TWS_{GRACE} due to groundwater extraction and aquifer storage depletion; changes in land cover/land use). In addition, TWS_{GRACE} signals in arid and semi-arid regions are so small that errors tend to be on par with signal size [13,127,128].

The relatively lower model performance in non-arid regions could be attributed to prolonged (e.g., decadal) climatic cyclicity that is not adequately represented in the model training period such as those reported in Eastern Africa [25], deforestation activities such as those reported in Central Africa [25], or absence of input variables that account for glaciers (e.g., Tibetan Plateau region) and surface water bodies (St. Lawrence basin) in locations where TWS_{GRACE} was reported to be dominated by glacier [129] and surface water [130] variabilities.

The leader model performance is significantly higher than that of any of the individual models (grid scale: $NSE = 0.65 \pm 0.20$, $CC = 0.81 \pm 0.13$, and $NRMSE = 0.56 \pm 0.16$; basin scale $NSE = 0.78 \pm 0.14$, $CC = 0.89 \pm 0.07$, and $NRMSE = 0.43 \pm 0.14$). The spatial distribution of the leader model results indicates that the DNN model outperforms both GLM

and GBM on the basin scale, whereas the GBM outperforms on the grid scale. The DNN model was selected as a leader model for 50% of the examined basins ($NSE = 0.75 \pm 0.17$, $CC = 0.88 \pm 0.09$, and $NRMSE = 0.46 \pm 0.16$). The GBM, on the other hand, was found to be a leader model for 47% of the examined grids ($NSE = 0.49 \pm 0.28$, $CC = 0.73 \pm 0.19$, and $NRMSE = 0.68 \pm 0.19$).

The performance of the basin-scale leader model is higher than that of the grid scale (in 58 basins). In addition, statistical measures of the basin scale reconstructions (e.g., average all of the model input and target variables) were higher ($NSE = 0.78 \pm 0.14$, $CC = 0.89 \pm 0.07$, and $NRMSE = 0.43 \pm 0.14$) compared to those estimated by averaging the grid-scale outputs over each of the investigated basins ($NSE = 0.67 \pm 0.12$, $CC = 0.82 \pm 0.07$, $NRMSE = 0.55 \pm 0.1$). This could be because both input and target variables averaged over basins with large spatial extent are smooth compared to the 1° grid scale [1].

Generally, the GBM tends to outperform the GLMs and DNN models in arid regions such as North Africa, Arabian Peninsula, and Central Asia. This could be related to the GBM's enhanced ability to predict the complex and nonlinear relationship between target and input variables. The GLM, however, works better in wet regions such as the Amazon, Central Africa, Indochina Peninsula, and the East European Plain. A possible explanation is the linear relationship between input variables and the TWS_{GRACE} in those regions. The DNN model was found to be the leader for all other areas.

The contribution of input variables varies greatly among the three models on both grid and basin scales. Spatially, $Annual_{GRACE}$ has a greater contribution in humid regions such as the Amazon, Central Africa, and northern Asia. The temperature plays a significant role in model performance in the eastern United States. On the other hand, TWS_{GLDAS} has a significant contribution everywhere. The dominant role of the TWS_{GLDAS} as a controlling factor could be because precipitation and temperature are already captured in the physics of the GLDAS model.

In addition to identifying the leader model as well as input variables that significantly control TWS_{GRACE} variability at each basin and grid point, this study provides better performance compared to some of the previous studies (Table 3). Out of the 28 published studies that used machine learning and statistical techniques to reconstruct TWS_{GRACE} data, this study's performance metrics were better than 61% and fair when compared to 21% of them. This is a conservative estimate since the performance of the grid-scale outputs in this study was compared to the other studies' basin-scale outputs. The latter is expected to have higher performance as explained above.

As with other studies, there are multiple sources of uncertainties associated with the TWS_{GRACE} reconstruction herein. These include uncertainties in target (e.g., TWS_{GRACE}) and input variables (e.g., rainfall, temperature, evapotranspiration, TWS_{GLDAS} , NDVI, ENSO, $Annual_{GRACE}$, and $Annual_{GLDAS}$). Errors in TWS_{GRACE} data include both measurements and leakage errors [131]. Both of these errors were reduced through the precise parameterization of the gravity field solutions and applications of coastlines filters and scaling factors [110]. Uncertainties in model inputs could be propagated from the training phase to the testing phase during the modelling process. These uncertainties were addressed by reporting of the average \pm a standard deviation of the performance measures (Sections 4.1 and 4.2) and errors in the reconstructed TWS_{GRACE} values (Figure 10). Other sources of uncertainties in the reconstructed TWS_{GRACE} data include unmolded human activities (e.g., irrigation, groundwater extraction, land use/land cover changes, etc.) that are challenging to find on a global grid scale. In addition, hyperparameters tuning for the employed models (GLM, GBM, and DNN) is challenging and time-consuming task especially when it comes to simulating a total of 14,310 global grid points. Unoptimized parameters, in some regions, might also introduce errors in the reconstructed TWS_{GRACE} estimates.

Table 3. Model testing performance comparison between this study and previous studies.

Reference	Region/Basin	Their Performance *	This Study
Becker et al. [38]	Amazon Basin	CC = 0.9	CC = 0.98
De Linage et al. [35]	Amazon Basin	R ² = 0.43	NSE = 0.95
Long et al. [33]	Southwest China	R ² = 0.57–0.91	NSE = 0.84–0.95
Sośnica et al. [46]	Global	Mean CC = 0.5	Mean CC = 0.81
Zhang et al. [64]	Yangtze Basin	NSE = 0.83	NSE = 0.84
Humphrey et al. [30]	Global	CC: Amazon = 0.96; Mississippi = 0.89; Volga = 0.90; Niger = 0.98	CC: Amazon = 0.98; Mississippi = 0.9, Volga = 0.93 Niger = 0.91
Yang et al. [41]	Northwest China	NSE = 0.2	NSE = 0.52
Chen et al. [28]	Northeast China	CC = 0.9	CC = 0.66
Ahmed et al. [25]	Africa	NSE = 0.54–0.94; CC = 0.79–0.97	NSE = 0.65–0.93; CC 0.82–0.97
Hasan et al. [39]	Africa	NSE = 0.72–0.94	NSE = 0.65–0.93
Humphrey and Gudmundsson [66]	Global	Median NSE < 0.5; CC < 0.75	Median NSE = 0.69; CC = 0.85
Ferreira et al. [67]	West Africa	CC = 0.88	CC = 0.91
Sun et al. [68]	India	CC = 0.94; NSE = 0.87	CC = 0.84; NSE = 0.71
Li et al. [53]	China	CC = 0.34–0.98; NSE = −0.21–0.95	CC = 0.44–0.95; NSE = 0.76–0.98
Jing et al. [69]	Nile River Basin	CC = ~0.9	CC = 0.91
Kenea et al. [31]	Ethiopia	R ² = 0.33–0.73; CC = 0.27–0.77	NSE = 0.1–0.93; CC = 0.38–0.97
Li et al. [32]	Global	Grid CC = 0.63; Basin CC = 0.6	Grid CC = 0.8; Basin CC = 0.89
Forootan et al. [48]	Global	CC = 0.89 (<i>p</i> = 0.00105)	CC = 0.8; <i>p</i> < 0.00001
Sun et al. [71]	Global	Basin NSE = 0.7; CC = 0.9; 58% of grids @ NSE > 0.4	Basin NSE = 0.78; CC = 0.89; 87% of grids @ NSE > 0.4
Sun et al. [42]	United States	CC = 0.95; NSE = 0.85	CC = 0.82; NSE = 0.67
Jing et al. [73]	Pearl River Basin	R ² = 0.56–0.71	NSE = 0.81
Sohoulande et al. [72]	United States	41.2% of area @ R ² > 0.5	82.1% of area @ NSE > 0.5
Jeon et al. [74]	Global	NSE = 0.14–0.9	NSE = 0.35–0.9
Yu et al. [75]	Canada	CC = 0.96	CC = 0.8
Tang et al. [76]	Lancang-Mekong River basin	Basin CC = 0.97; Grid CC = 0.9	Basin CC = 0.98; Grid CC = 0.89
Yang et al. [77]	Australia	NSE = 0.96, CC = 0.98	NSE = 0.66; CC = 0.81
Gyawali et al. [20]	Texas Gulf Coast	CC = 0.85, NSE = 0.73	CC = 0.83; NSE = 0.67
Mo et al. [78]	Global	40 basins NSE = 0.44–0.96	62 basins NSE = 0.44–0.97

* CC: correlation coefficient, NSE: Nash–Sutcliffe efficiency coefficient, R²: coefficient of determination, *p*: *p*-value.

The developed approach is robust, effective, and advantageous. Unlike the previous studies [32,71] that used similar data-driven and machine learning techniques, our approach defines the leader model for each basin and grid point. The leader model as well as input variables that significantly control TWS_{GRACE} variability, were globally quantified, for both basin and grid scales, previously performed only for the conterminous United States [42]. This study's approach offers the capability to reconstruct the TWS_{GRACE} data over small basins and grids (1° × 1°) with high accuracy. Therefore, it helps overcome a limitation that hinders the application of gravimetric datasets (e.g., SLR and Swarm) to small-scale regions given their coarse spatial resolution [42]. When compared to data assimilation techniques [82,83,86] that utilize computationally extensive complex algorithms, the approach herein is computationally efficient and can be utilized on regular computers.

6. Conclusions

This study reviewed the different approaches available in the literature to reconstruct and fill temporal gaps in the TWS_{GRACE} record. The study also provided a new approach to fill current gaps in the TWS_{GRACE} record (20 months), between the GRACE and GRACE-FO missions (11 months), and within the GRACE-FO record (2 months) from April 2002 through to April 2020. The proposed approach compared the performance of three machine learning models (GLM, GBM, and DNN) in reconstructing the TWS_{GRACE} data at both grid ($1^\circ \times 1^\circ$; total: 14,310) and basin (62 global watersheds) scales. Eight variables were used to reconstruct the TWS_{GRACE} data. The model performance was assessed during the training and testing phases using three statistical measures (e.g., NSE, CC, and NRMSE) and a leader model, that showed the highest statistical performance during the testing phase, was selected for each grid and basin. The relative importance of each of the input variables was also investigated.

Results indicate that the leader model reconstructed the TWS_{GRACE} with high accuracy over both grid and local scales, particularly in wet regions and those with low anthropogenic impacts. The reconstructed TWS_{GRACE} data captured extreme climatic events over the investigated basins and grid cells. However, no single model could be used in reconstructing the TWS_{GRACE} over all grids or basins and a combination of models is recommended. Despite the effectiveness of the developed approach, the adopted models exhibit a relatively poor performance in arid and semi-arid regions because they do not incorporate anthropogenic activities as model inputs. This may also be the result of lower signal-to-noise ratio of the TWS_{GRACE} in arid versus humid regions.

According to the most recent National Academy of Sciences Decadal Survey for Earth Science and Applications from Space [132], mass change “within and between the Earth’s atmosphere, oceans, groundwater, and ice sheets” has been recognized as an essential part of observing the Earth system and recognized as a “Designated Observable.” While the Decadal Survey emphasized the importance of measuring mass continuity changes, it is still possible that the GRACE-FO mission, which was designed to have a nominal life of 5 years (2018–2023), could fail prior to the launch of the next mass-change observing system, for which a target launch date has not yet been set. Therefore, there is a fundamental need to predict and/or infer mass change from other variables, even beyond the current gaps.

The developed approach can serve as a reference tool to fill TWS_{GRACE} data gaps in GRACE and GRACE-FO missions. The model performance can be improved particularly in arid and semi-arid regions by incorporating the anthropogenic impact variables into the model inputs. In addition, the presented new approach could be used to reconstruct TWS_{GRACE} for the pre-GRACE era. A long-term and uninterrupted TWS_{GRACE} record could also be used to enhance the groundwater monitoring and other hydrological and climatic processes across the globe.

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Appendix A

Table A1. Characteristics of global 62 major river basins used in this study.

Basin ID	Basin Name	Continent	Precipitation (mm/yr)	Area (km ²)	Climate Zone
0	Nile	Africa	704	3,271,155	Dry
1	Niger	Africa	704	2,277,159	Dry
2	Lake Chad	Africa	396	2,660,764	Dry
3	Zaire	Africa	1556	3,735,917	Tropical
4	Zambezi	Africa	980	1,472,701	Temperate
5	Okavango	Africa	561	971,144	Dry
6	Limpopo	Africa	537	487,829	Dry
7	Mozambique NE Coast	Africa	833	278,592	Tropical
8	Ruvuma	Africa	1017	1,071,358	Tropical
9	Volta	Africa	1016	425,491	Tropical
10	Churchill	North America	499	981,996	Continental
11	Saskatchewan-Nelson	North America	548	2,836,224	Continental
12	Fraser	North America	706	620,355	Continental
13	St. Lawrence	North America	1051	2,149,625	Continental
14	Columbia	North America	613	1,367,203	Continental
15	Colorado	North America	320	978,636	Dry
16	Mississippi	North America	884	5,625,053	Temperate/Continental
17	Mackenzie	North America	481	1,992,763	Continental
18	Magdalena	South America	2342	263,197	Tropical
19	Orinoco	South America	2374	944,775	Tropical
20	Amazon	South America	2263	6,025,286	Tropical
21	Tocantins	South America	1663	803,661	Tropical
22	Parnaiba	South America	1047	337,411	Tropical
23	Sao Francisco	South America	976	673,366	Tropical
24	Uruguay	South America	1795	347,840	Temperate
25	Parana	South America	1309	3,065,761	Tropical
26	Rio Colorado	South America	332	434,140	Dry

Table A1. Cont.

Basin ID	Basin Name	Continent	Precipitation (mm/yr)	Area (km ²)	Climate Zone
27	Flinders	Australia	286	971,231	Dry
28	Murray	Australia	521	1,040,403	Dry/Temperate
29	Lena	Asia	457	1,453,767	Continental
30	Yenisei	Asia	451	4,177,460	Continental
31	Ob1	Asia	668	2,221,313	Continental
32	Lena	Asia	575	898,935	Continental
33	Ob2	Asia	529	1,681,026	Continental
34	Ob3	Asia	560	921,174	Continental
35	Amur	Asia	622	4,776,036	Continental
36	Ili	Asia	370	846,829	Continental/Dry
37	Syr Darya	Asia	387	596,945	Dry
38	Amu Darya	Asia	324	1,050,574	Dry
39	Tarim (Yarkand)	Asia	112	1,539,641	Dry
40	Yodo	Asia	531	346,578	Continental
41	Hwang Ho	Asia	490	1,251,658	Continental/Dry
42	Yangtze	Asia	1094	2,584,657	Temperate
43	Indus	Asia	535	1,202,195	dry
44	Narmada	Asia	409	401,453	Dry
45	Ganges-Brahmaputra	Asia	1293	2,001,344	Temperate
46	Si	Asia	1502	486,550	Temperate
47	Godavari	Asia	1165	347,993	Tropical
48	Salween	Asia	1113	327,489	Temperate
49	Irrawaddy	Asia	1802	447,888	Tropical/Temperate
50	Krishna	Asia	932	280,322	Tropical/Dry
51	Mekong	Asia	1581	871,453	Tropical
52	Don	Europe	722	1,055,369	Continental
53	Ural	Europe	489	540,152	Continental
54	Dnieper	Europe	786	1,308,031	Continental
55	Volga	Europe	777	4,535,995	Continental
56	Danube	Europe	917	1,653,884	Temperate
57	Murghab/Hari Rud	Asia	257	465,732	Dry
58	Helmand	Europe	241	285,431	Dry
59	Tigris-Euphrates	Asia	380	1,253,767	Dry
60	Saudi Arabia	Asia	80	275,525	Dry
61	Yemen	Asia	66	232,406	Dry

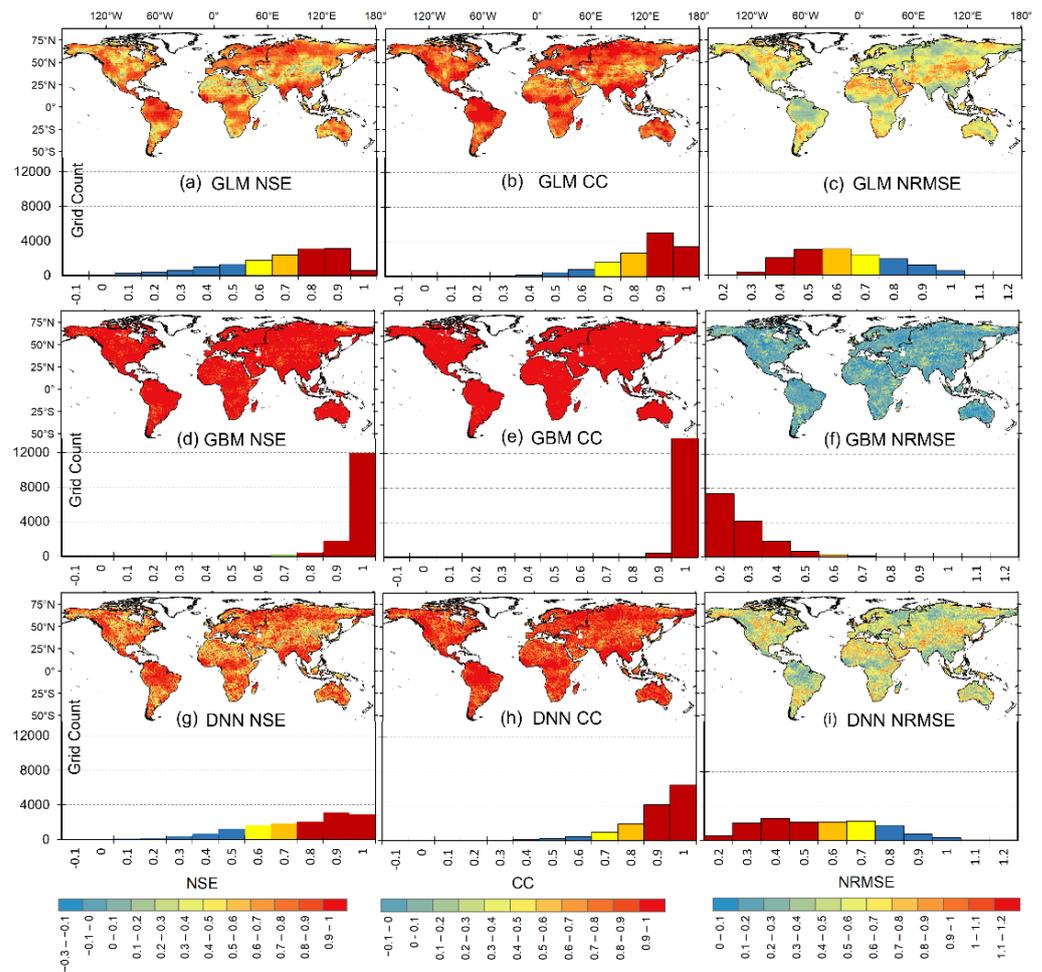


Figure A1. Spatial (maps) and frequency (bar plots) distributions of the grid-scale training performance for the (a–c) GLMs, (d–f) GBM models, and (g–i) DNN models. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

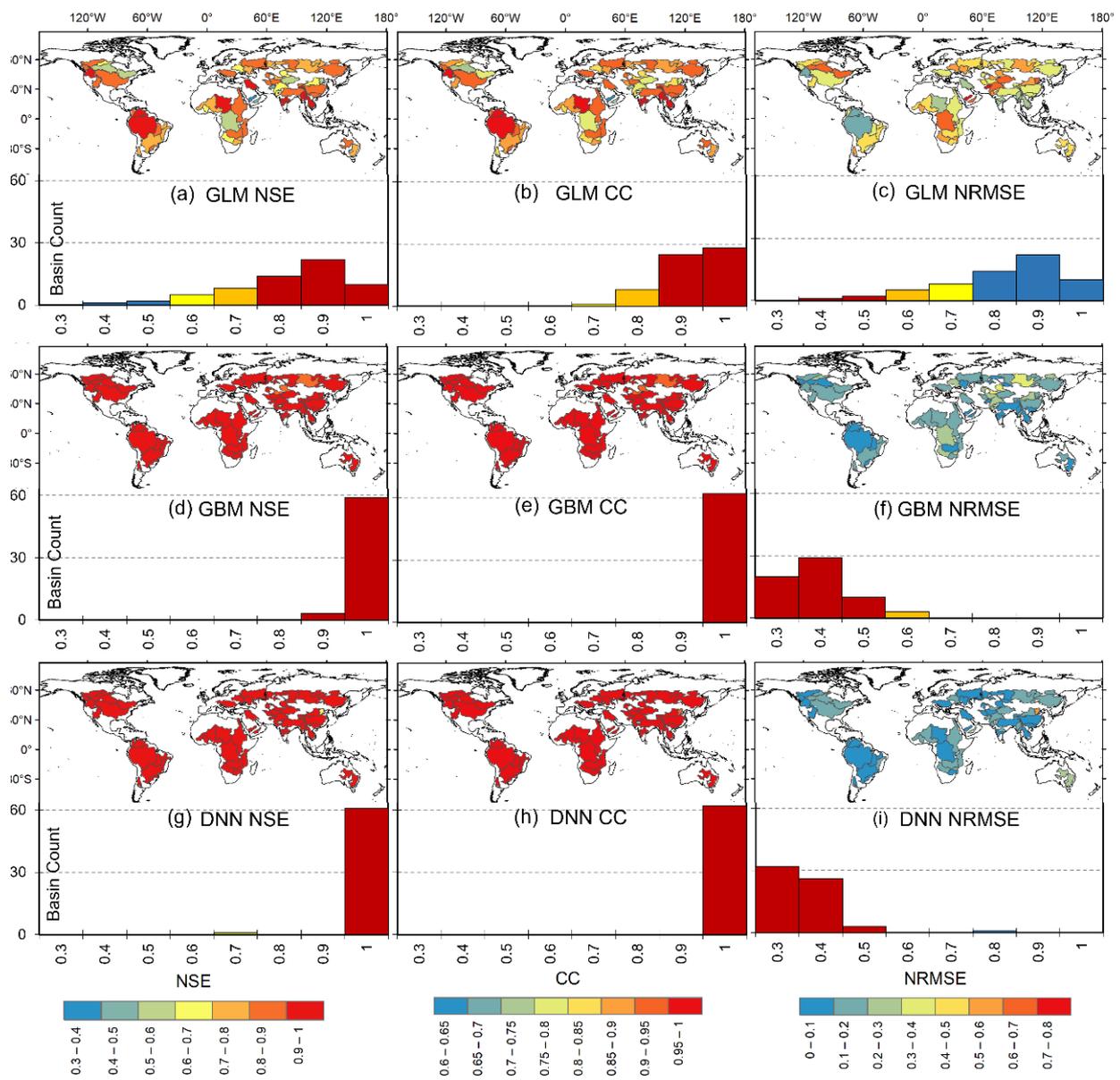


Figure A2. Spatial (maps) and frequency (bar plots) distributions of the basin-scale training performance for the (a–c) GLMs, (d–f) GBM models, and (g–i) DNN models. The color-coded frequency distribution shows the very good (red), good (orange), satisfactory (yellow), and poor (blue) performance categories.

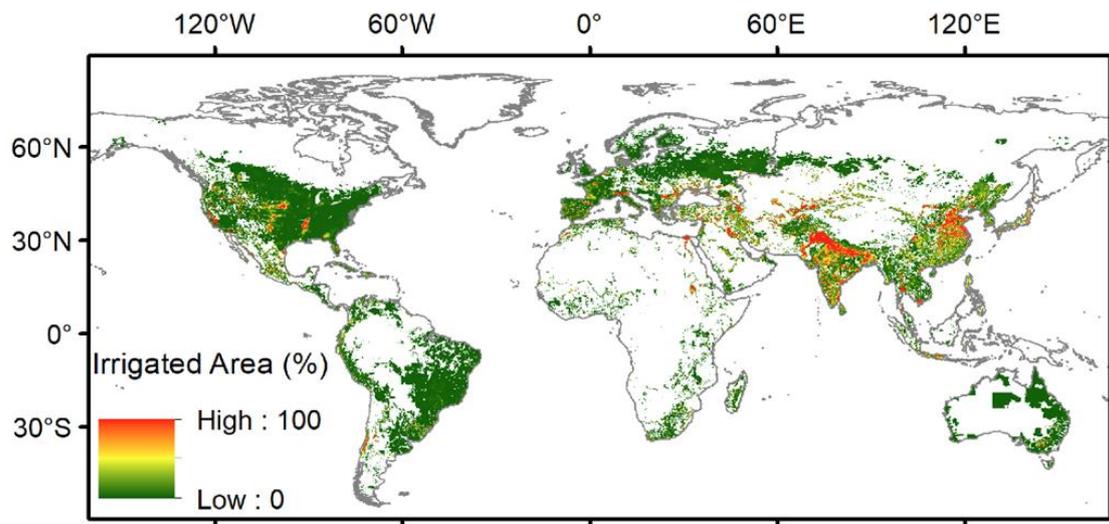


Figure A3. Global map of irrigated areas provided by the Food and Agricultural Organization [133].

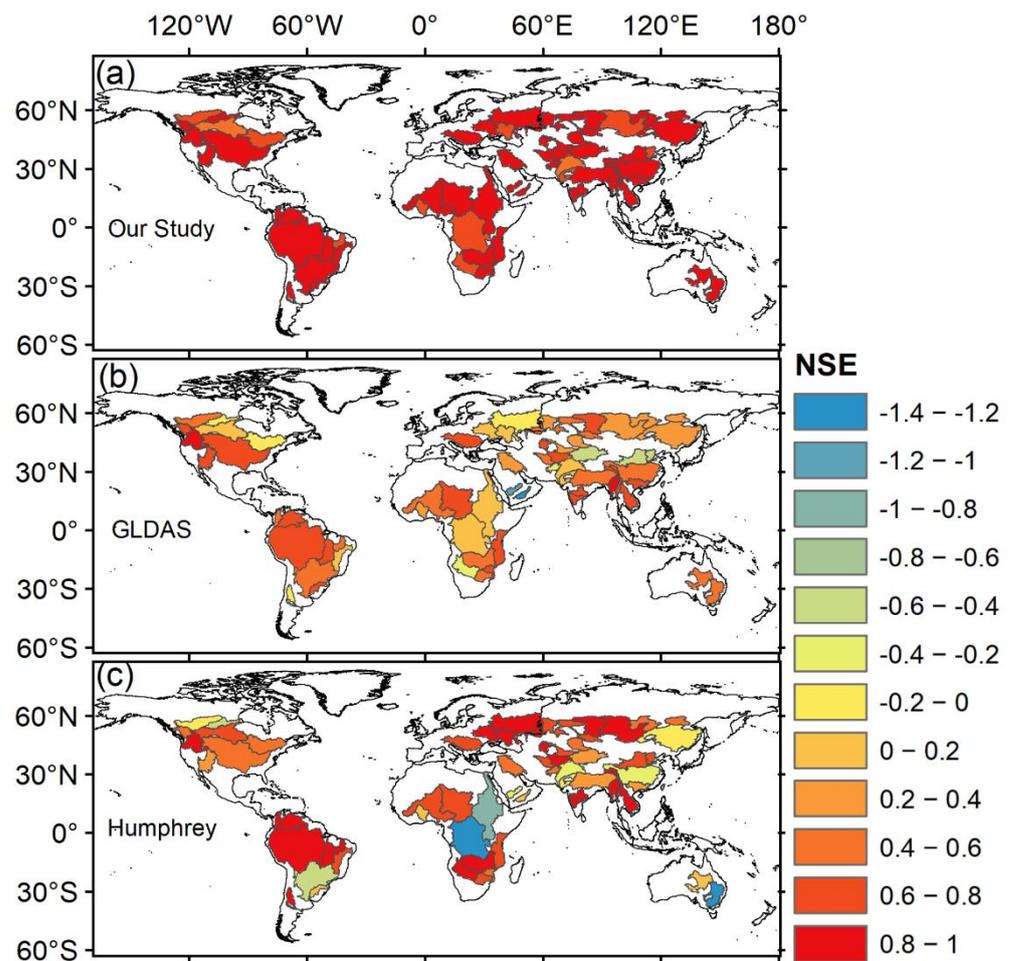


Figure A4. Basin Scale NSE values between TWS_{GRACE} and this study (a), TWS_{GLDAS} (b), and $TWS_{Humphrey}$ (c). The NSE was calculated using data from 2002–2019.

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